

ebm-papst Inc.
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Farmington, CT 06034
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Nominal Data

Model	EG1R240310A	
Motor	M3G112-GA	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	3955
Power consumption	W	3159
Current draw	A	8.4
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

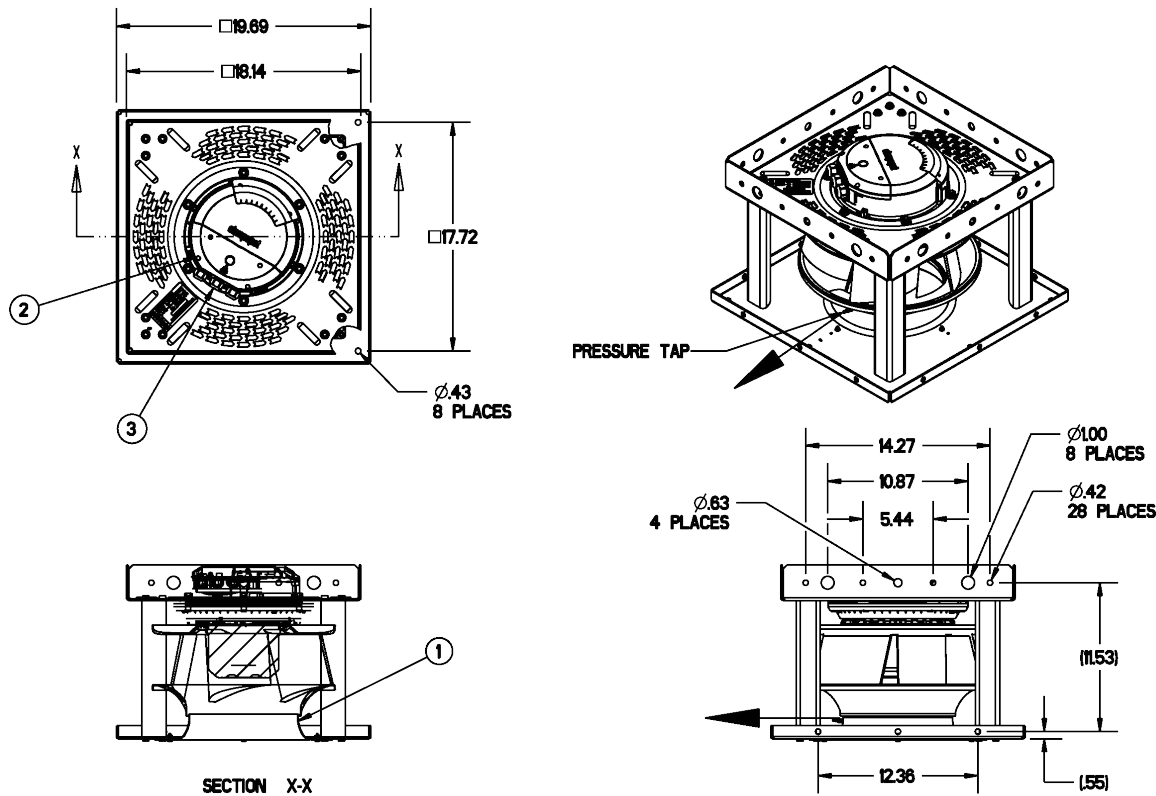
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	61 lb (27.7 kg)
Nominal Impeller Size	12.2 in (310 mm)
Motor size	112
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

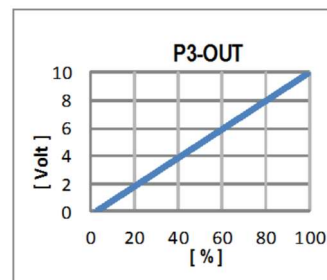
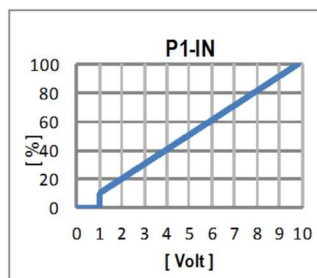
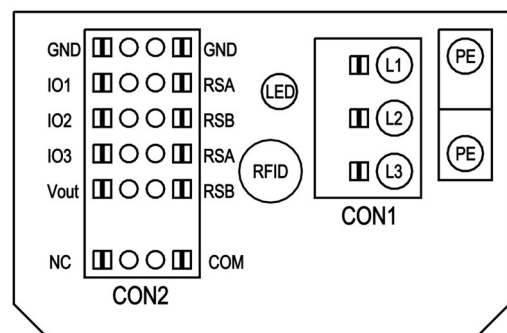
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 116 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79310-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 25311-2-2957 (not included in scope of delivery)

Electrical Interface



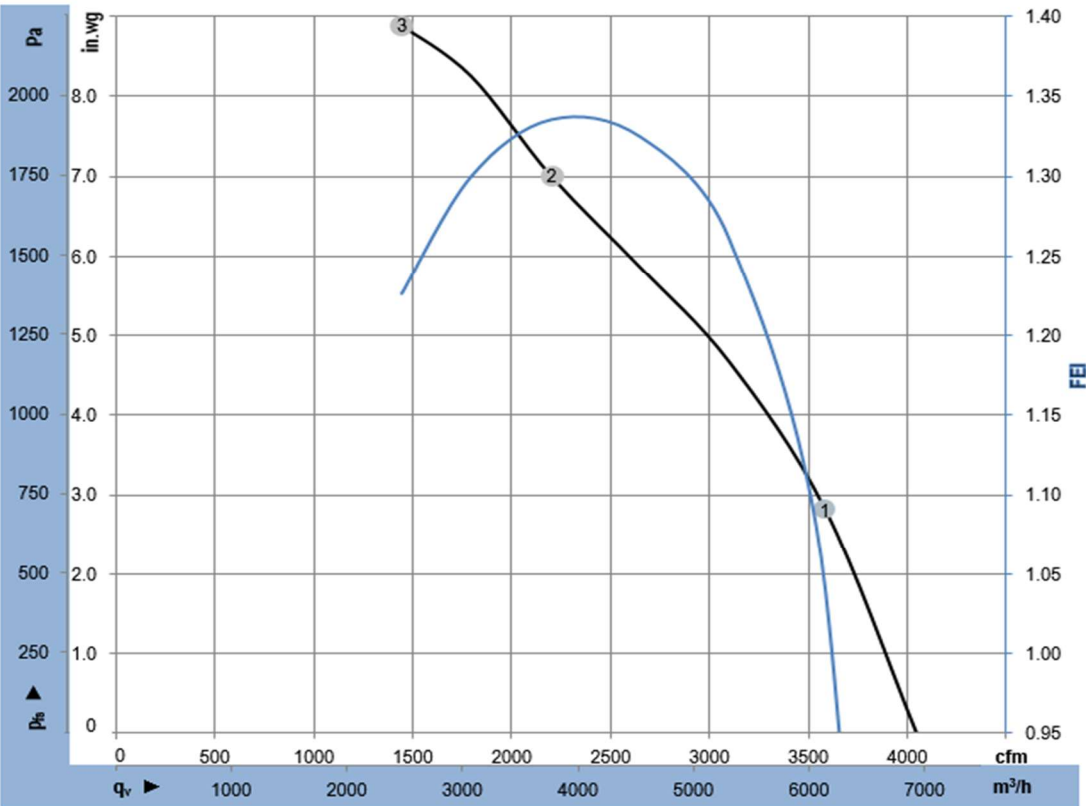
No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

Terminal assignment

		configurable IO		configurable IO mode		electrical specification		MODBUS Register for IO mode configuration		configurable IO functions: normal / inverse		INPUT		OUTPUT																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																											
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◦ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.3



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-1839

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	4002	2786	7.4	3586	2.8	1.04
2	3~	230	60	3905	3132	8.4	2203	7.0	1.34
3	3~	230	60	4001	2981	7.9	1448	8.9	1.23

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480310A	
Motor	M3G112-GA	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	3975
Power consumption	W	3132
Current draw	A	4.3
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
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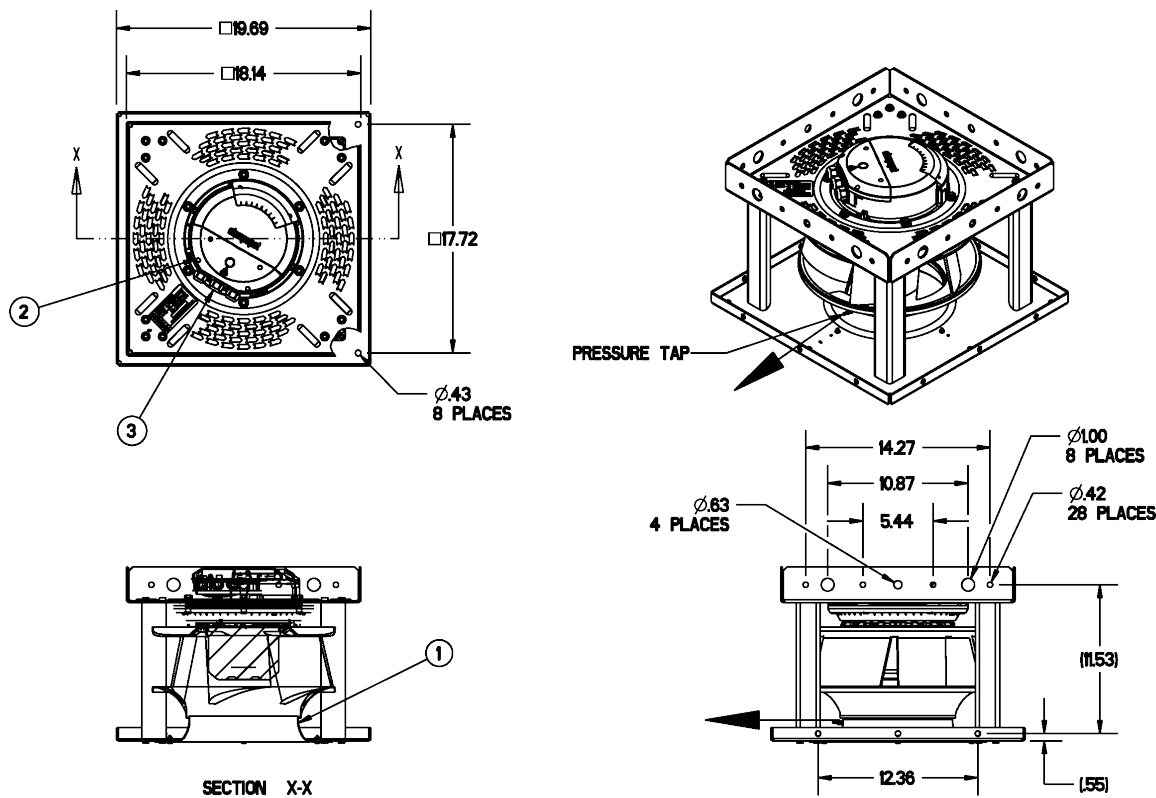
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Motor size	112
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Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
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Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
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Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
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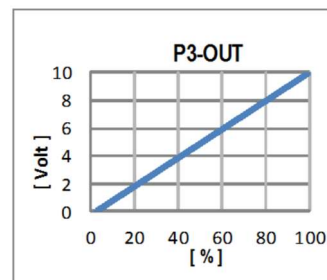
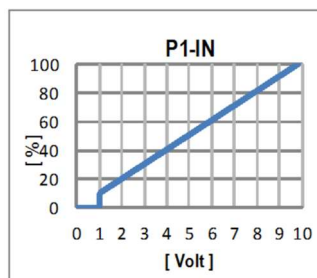
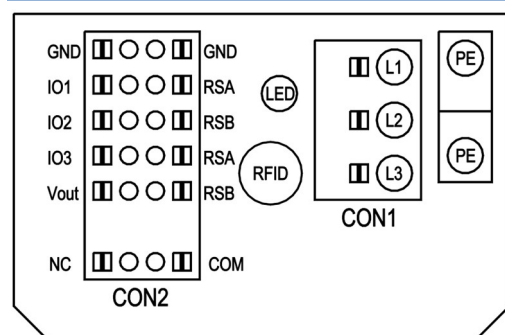
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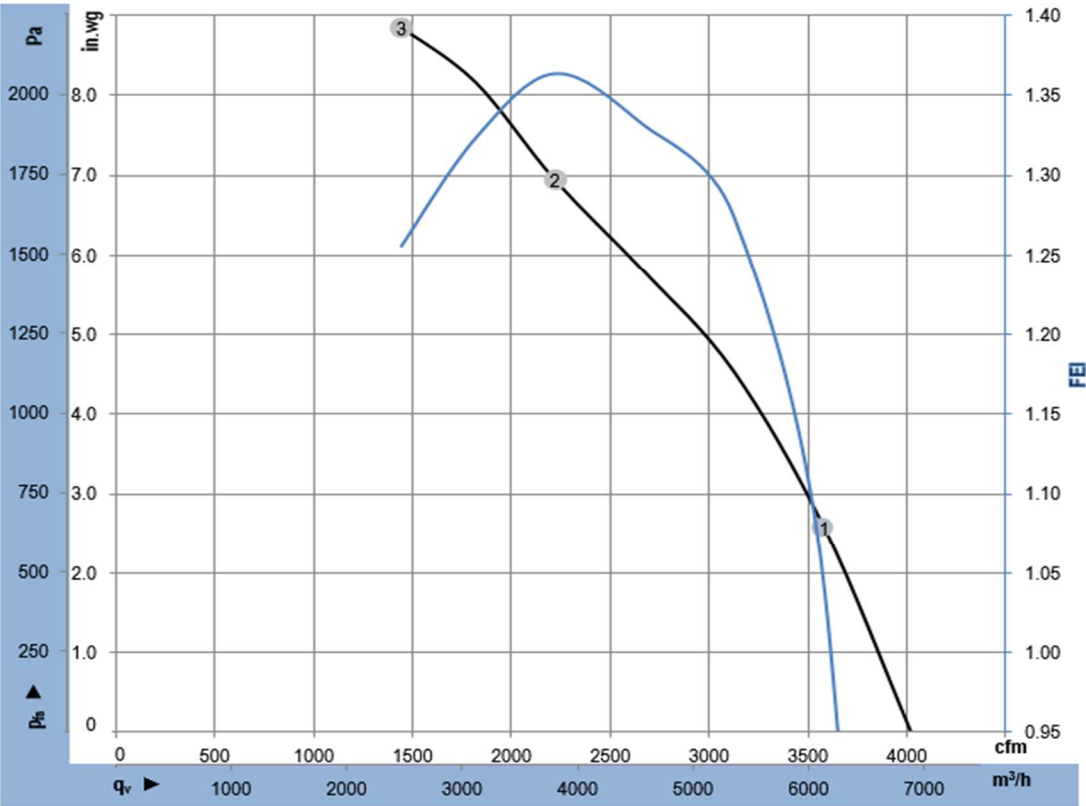
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		P3-OUT	Output characteristic curve

Terminal assignment

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○ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.3



$\rho = 0.075 \text{ lbm/ft}^3$
Measurement: LU-1832
ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	4003	2588	3.6	3584	2.6	1.04
2	3~	460	60	3940	3066	4.2	2221	6.9	1.36
3	3~	460	60	4000	2895	3.9	1446	8.8	1.26

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Farmington, CT 06034
sales@us.ebmpapst.com
www.ebmpapst.us

Nominal Data

Model	EG1R240355A	
Motor	M3G112-GA	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	3230
Power consumption	W	3012
Current draw	A	8.0
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

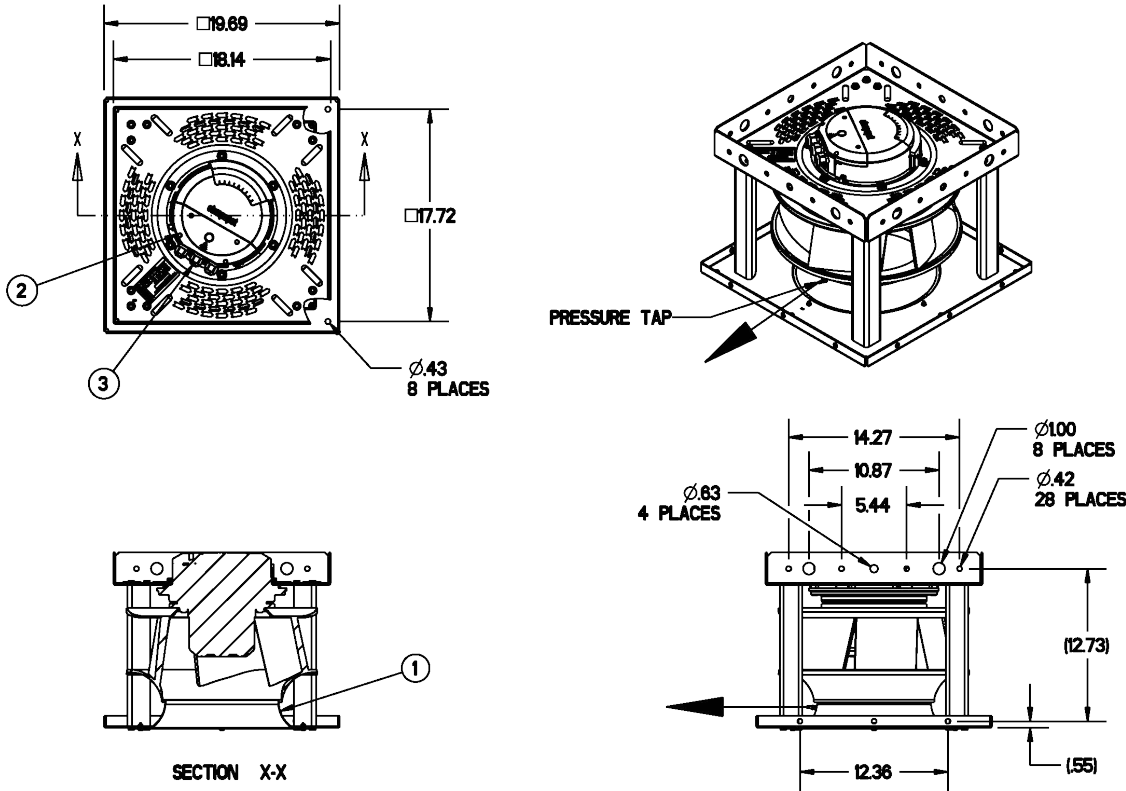
ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description	
Weight	61.2 lb (27.8 kg)
Nominal Impeller Size	14 in (355 mm)
Motor size	112
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

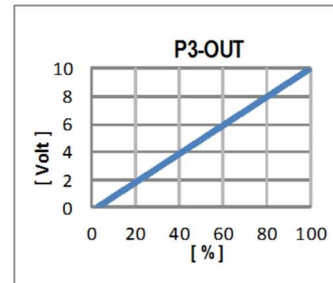
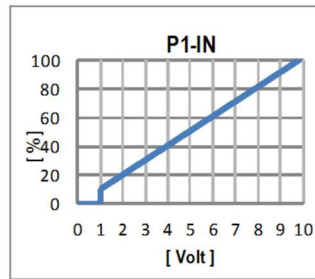
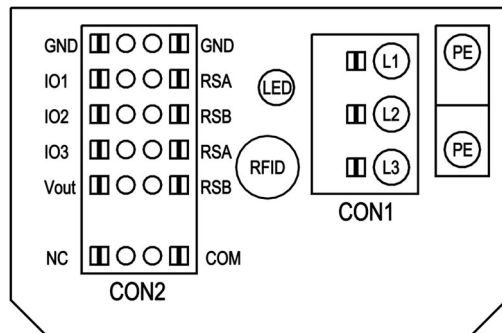
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 148 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79355-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00401-2-2957 (not included in scope of delivery)

Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 V / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 V, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

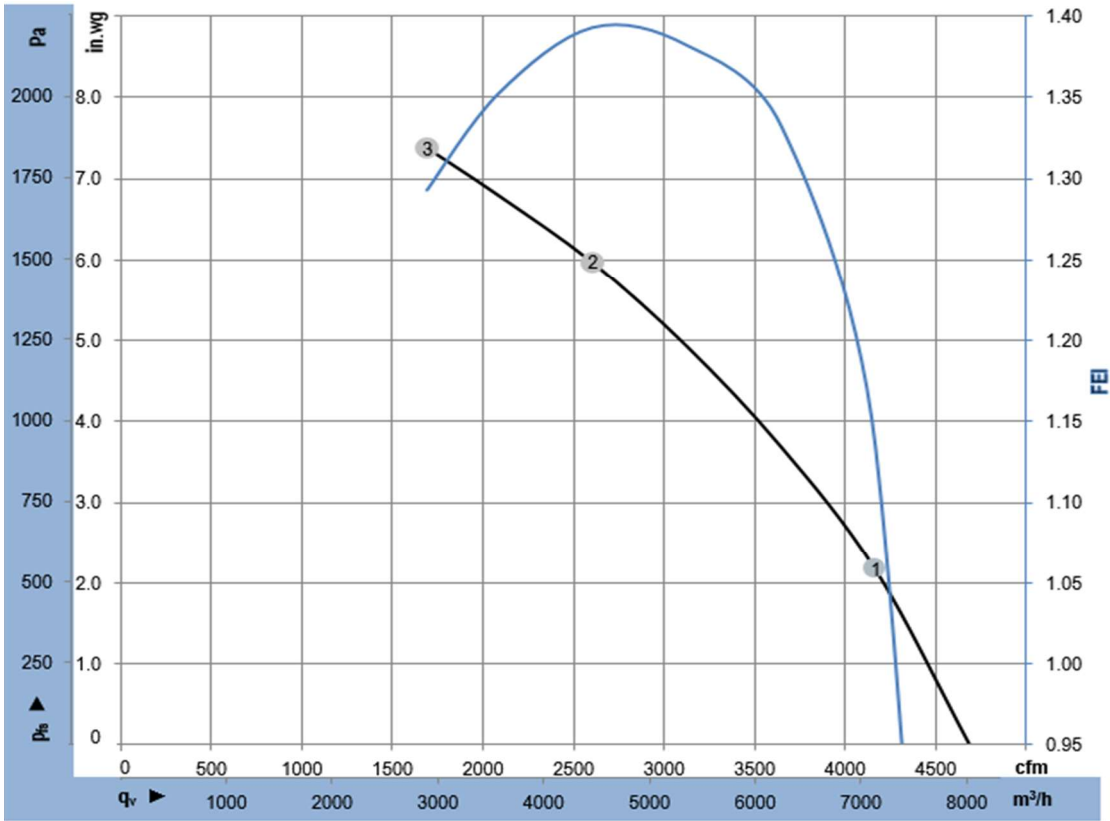
Terminal assignment

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○ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App,
or MODBUS Parameter Specification V6.3

	voltage output alternatively: input auxiliary power supply for parameterization via RS485/MODBUS RTU without line voltage	voltage parameterizable 3.3...24VDC \pm 5%, P _{max} =800mW, short-circuit-proof, supply for external devices, SELV 15...50VDC	D16E [...]
Vout			
RSA RSB	RS485 bus connection,	MODBUS RTU, specification V6.3, SELV	
IO3	○ Din3 (active high): digital input	active: applied voltage 3.5-50VDC, SELV not active: pin open or applied voltage < 1.5VDC	D15A [0]
	○ Din3 (active low): digital input	active: applied voltage < 1.5VDC, SELV not active: pin open or applied voltage 3.5-50VDC	D15A [1]
	○ PWM in3: digital input idle level high	PWM = 40Hz - 10kHz, characteristics parameterizable active: pin open or applied voltage 3.5-50VDC not active: applied voltage < 1.5VDC, SELV	D15A [7]
	○ PWM in3: digital input idle level low	40Hz - 10kHz, characteristics parameterizable active: applied voltage 3.5-50VDC not active: pin open or applied voltage < 1.5VDC, SELV	D15A [8]
	○ Aout3 0-10V: analog output	function parameterizable, max. 5mA max output frequency 300Hz, SELV	D15A [4]
	○ Tacho out (pulses), analog output	0-10V max. 5mA, max output frequency 300Hz, SELV	D15A [5]
	○ Diagnostics out (pulses)	0-10V max. 5mA, max output frequency 300Hz, SELV	D15A [6]



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-2090

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	3230	2361	6.4	4172	2.2	1.13
2	3~	230	60	3226	3012	8.0	2608	6.0	1.39
3	3~	230	60	3230	2721	7.3	1695	7.4	1.29

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480355A	
Motor	M3G112-GA	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	3230
Power consumption	W	3056
Current draw	A	4.2
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

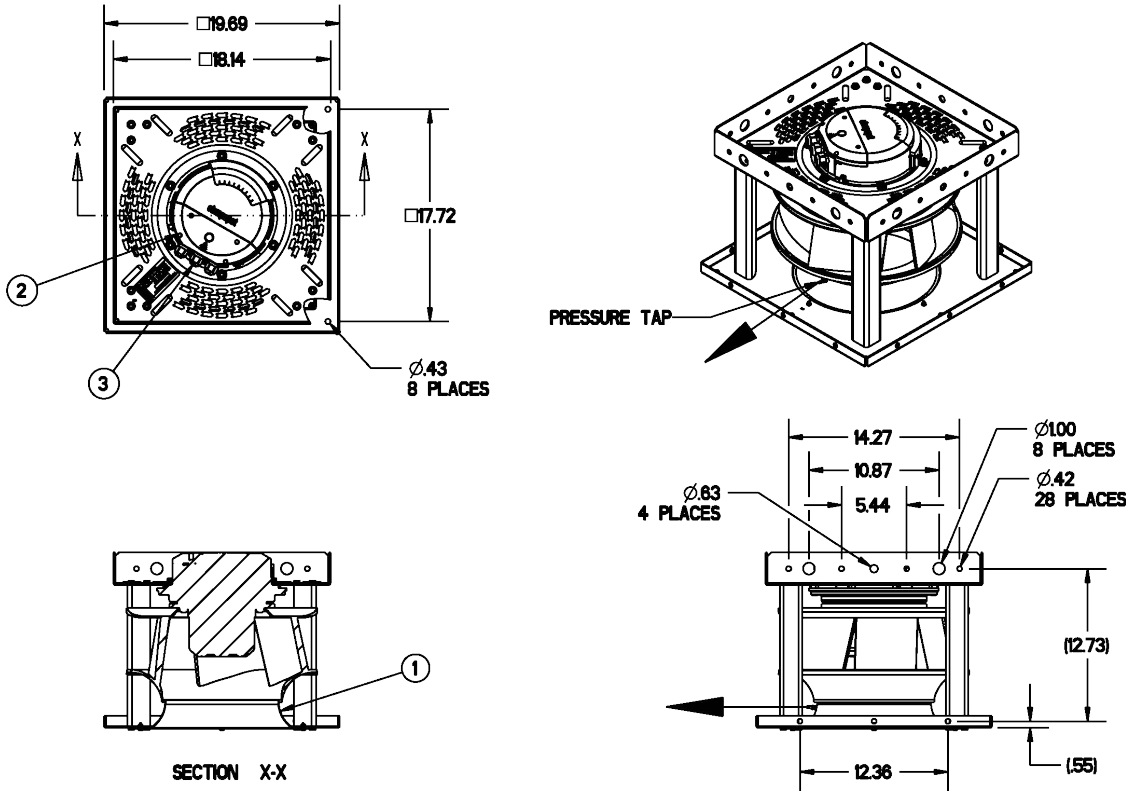
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	61.2 lb (27.8 kg)
Nominal Impeller Size	14 in (355 mm)
Motor size	112
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

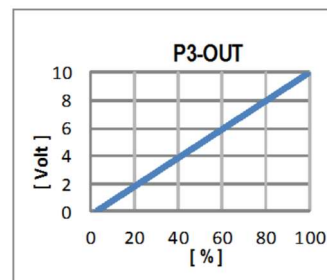
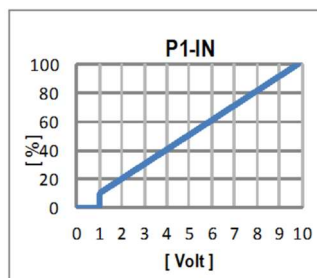
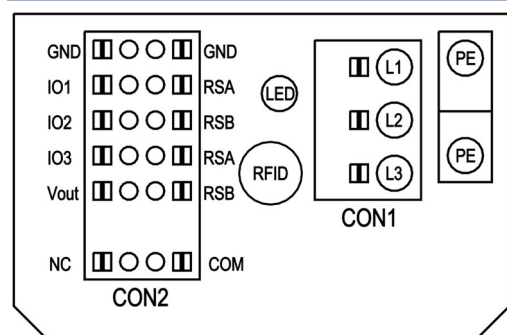
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 148 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79355-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00401-2-2957 (not included in scope of delivery)

Electrical Interface



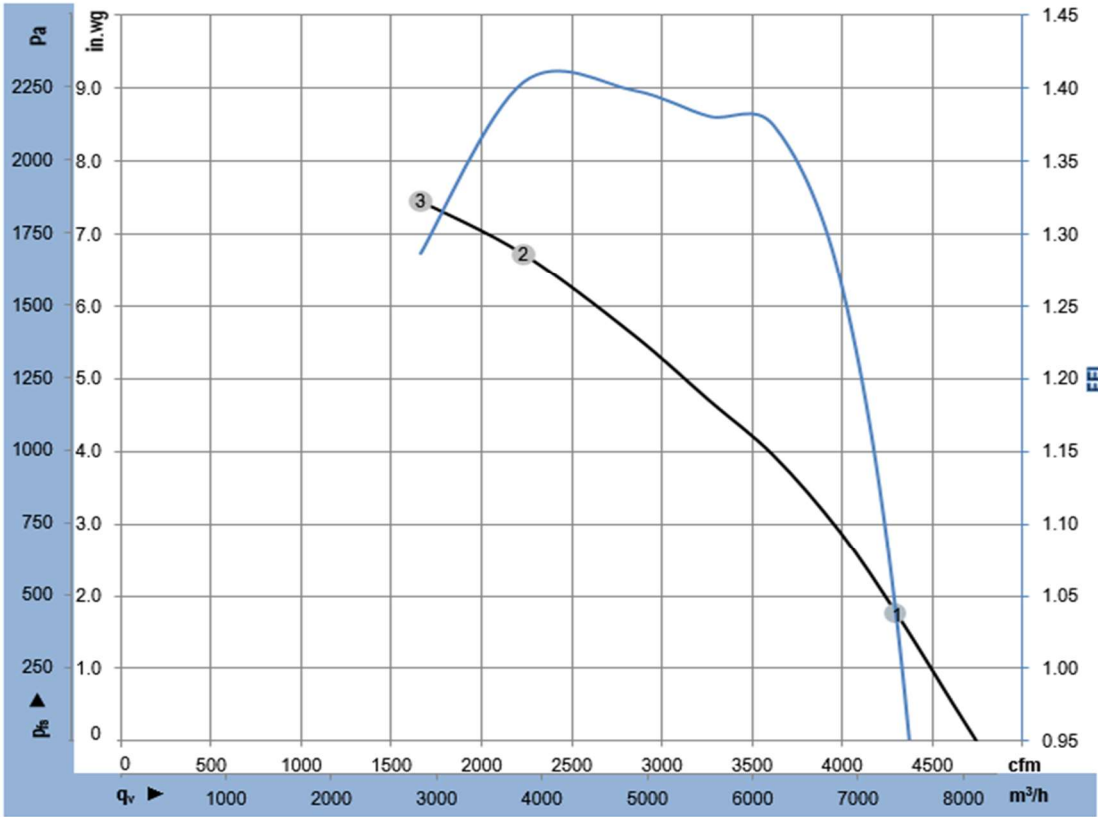
No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

Terminal assignment

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○ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.3



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-1820

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	3231	2254	3.2	4306	1.7	1.03
2	3~	460	60	3232	2906	4.0	2232	6.7	1.40
3	3~	460	60	3227	2715	3.7	1663	7.5	1.29

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R240400A	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2800
Power consumption	W	3869
Current draw	A	10.3
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	131 (55)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

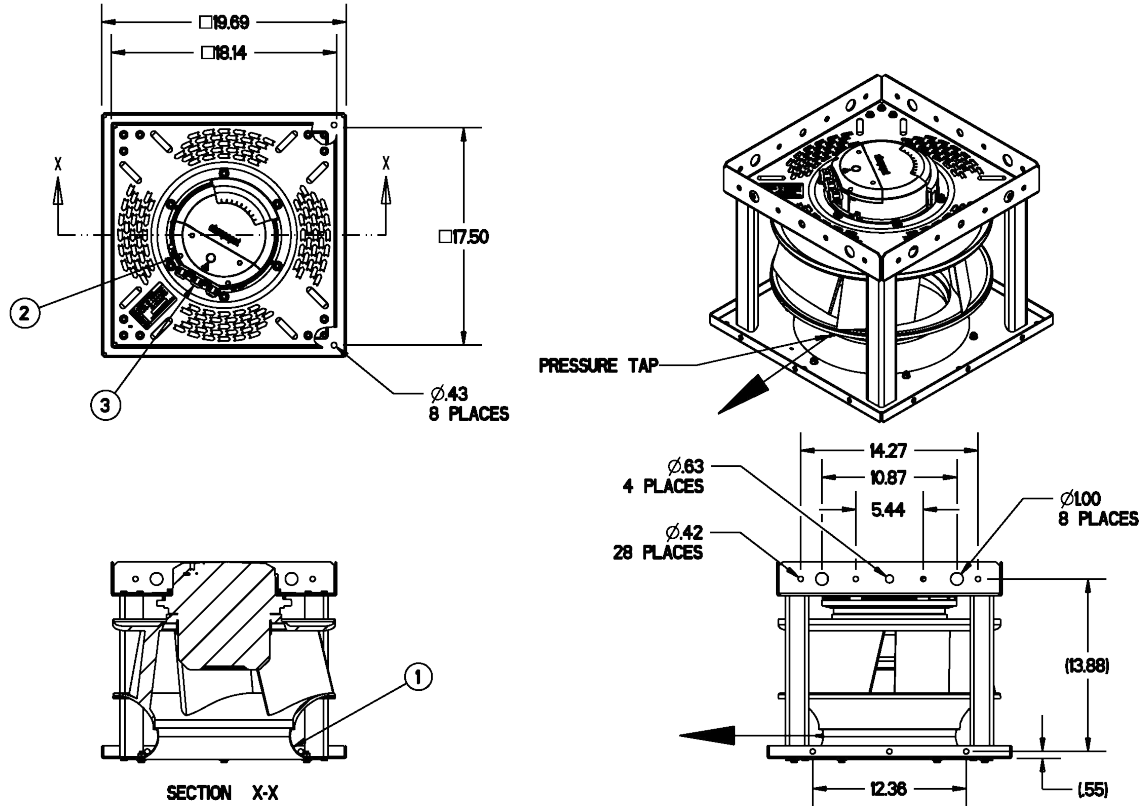
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	72 lb (32.7 kg)
Nominal Impeller Size	15.7 in (400 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

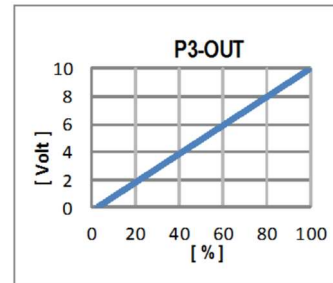
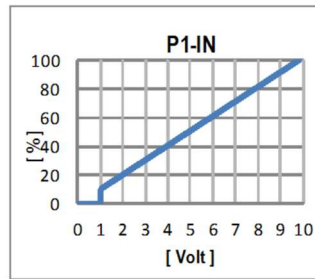
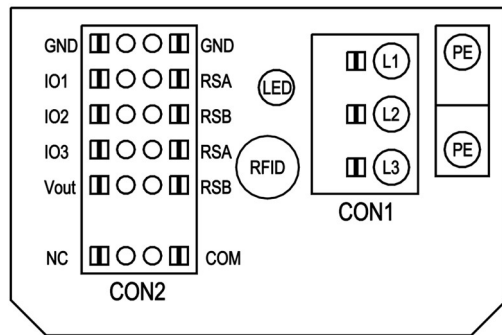
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 188 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79400-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 V / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 V, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

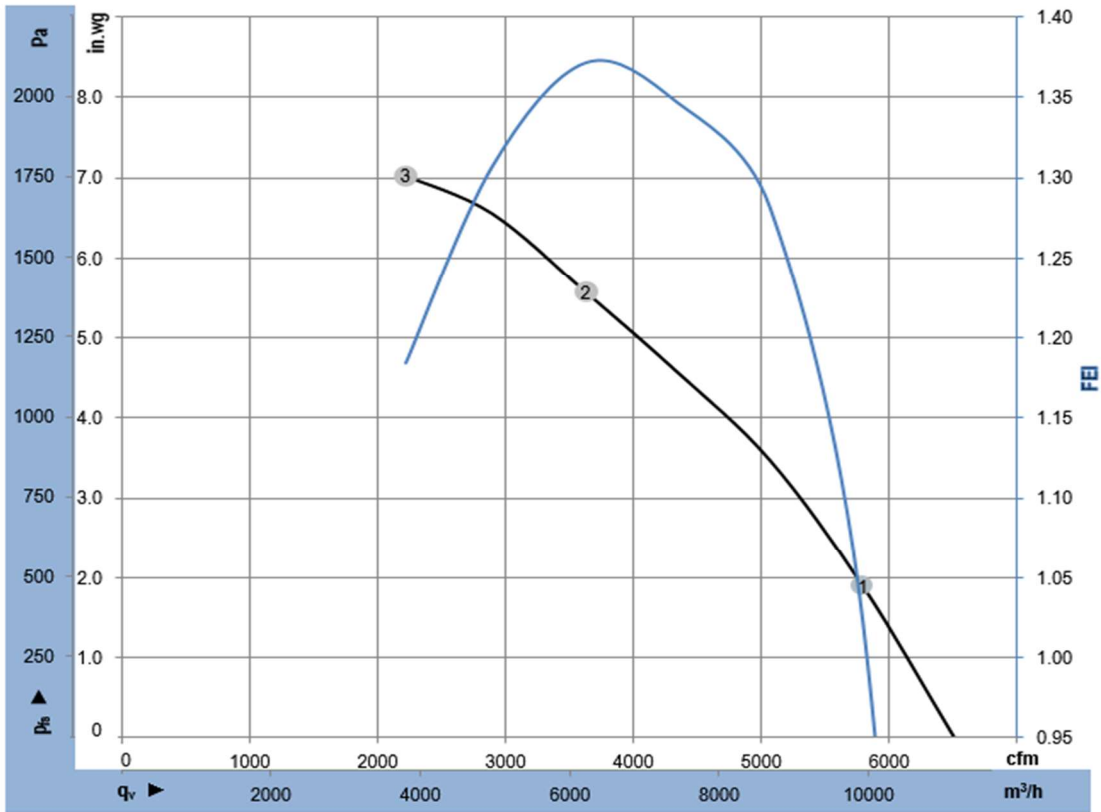
Terminal assignment

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o configurable option

For further information and additional functions see EC Control Software, Fan-Set-App,
or MODBUS Parameter Specification V6.3

CON2	configurable IO mode	electrical specification	configurable IO functions: normal / inverse
IO1	o Din1 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D158 [0]
	o Ain1 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV	D158 [2]
	o Tach out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV	D158 [5]
	o Diagnostics out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV	D158 [6]
IO2	o Din2 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D159 [0]
	o Ain2 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV	D159 [2]
	o Ain2 4-20mA: analog input	Ri = 125R, characteristic curve parameterizable, SELV	D159 [3]
	o Din3 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D15A [0]
IO3	o Din3 (active low): digital input	active: applied voltage < 1,5VDC, SELV not active: pin open or applied voltage 3,5-50VDC	D15A [1]
	o PWMIn3: digital input idle level high	PWM = 40Hz - 10kHz, characteristics parameterizable active: pin open or applied voltage 3,5-50VDC not active: applied voltage < 1,5VDC, SELV	D15A [7]
	o PWMIn3: digital input idle level low	40Hz - 10kHz, characteristics parameterizable active: applied voltage 3,5-50VDC not active: pin open or applied voltage < 1,5VDC, SELV	D15A [8]
	o Aout3 0-10V: analog output	function parameterizable, max. 5mA max output frequency 300Hz, SELV	D15A [4]
	o Tacho out (pulses), analog output	0-10V max. 5mA, max output frequency 300Hz, SELV	D15A [5]
	o Diagnostics out (pulses)	0-10V max. 5mA max output frequency 300Hz, SELV	D15A [6]
RSA RSB	RS485 bus connection,	MODBUS RTU, specification V6.3, SELV	
Vout	voltage output	voltage parameterizable 3,3...24VDC +/- 5%, Pmax=800mW, short-circuit-proof, supply for external devices, SELV	D16E [...]
	alternatively: Input auxiliary power supply for parameterization via RS485/MODBUS RTU without line voltage	15...50VDC	



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-2088

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	2800	3168	8.5	5797	1.9	1.02
2	3~	230	60	2784	3850	10.2	3627	5.6	1.37
3	3~	230	60	2803	3565	9.5	2220	7.0	1.18

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480400A	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2800
Power consumption	W	3950
Current draw	A	5.3
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

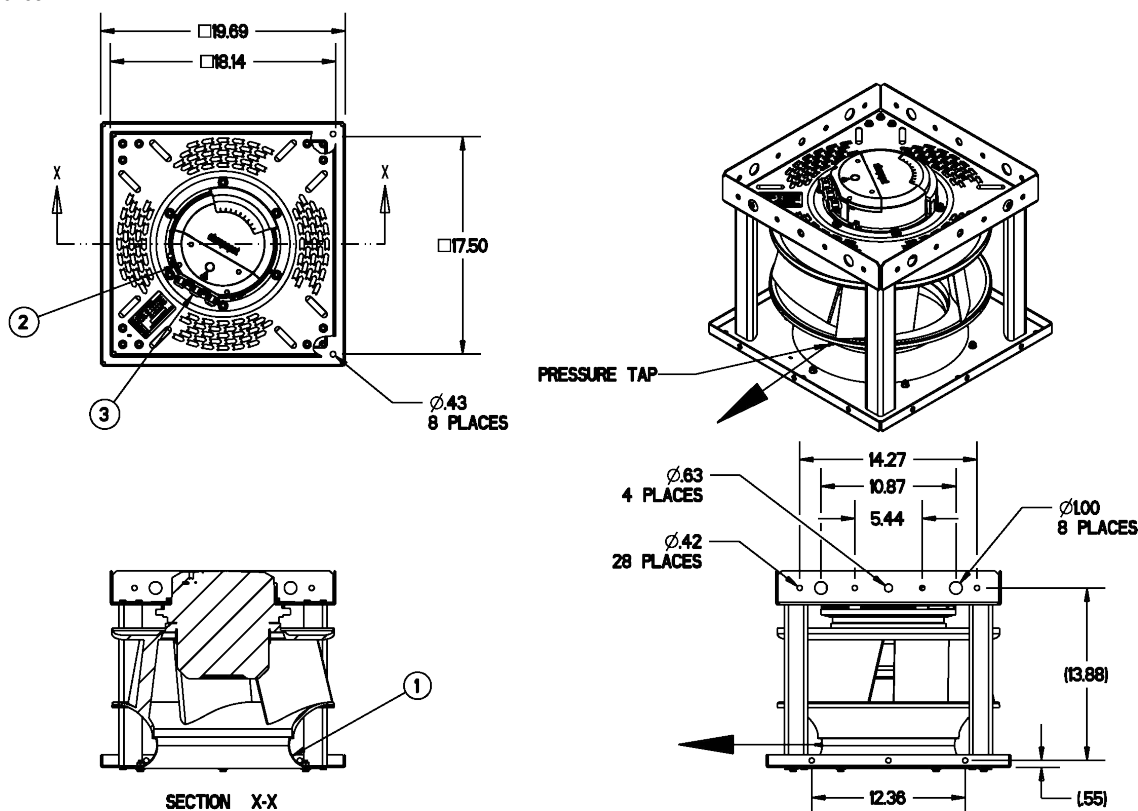
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	77.4 lb (35.1 kg)
Nominal Impeller Size	15.7 in (400 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

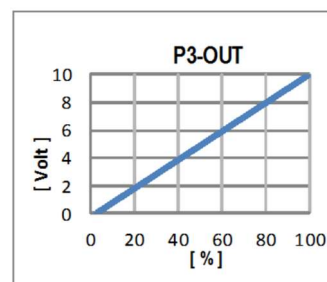
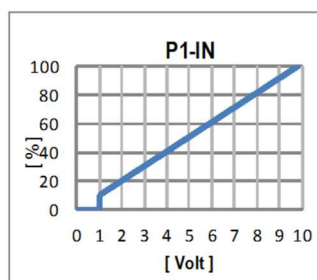
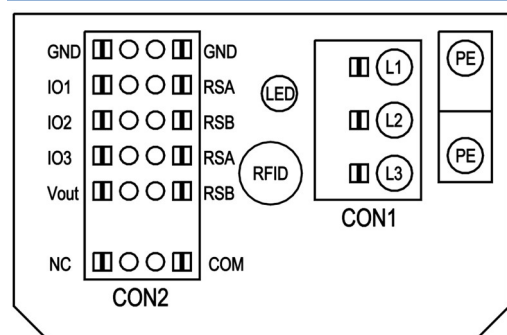
Product drawing

Dimensions in inches



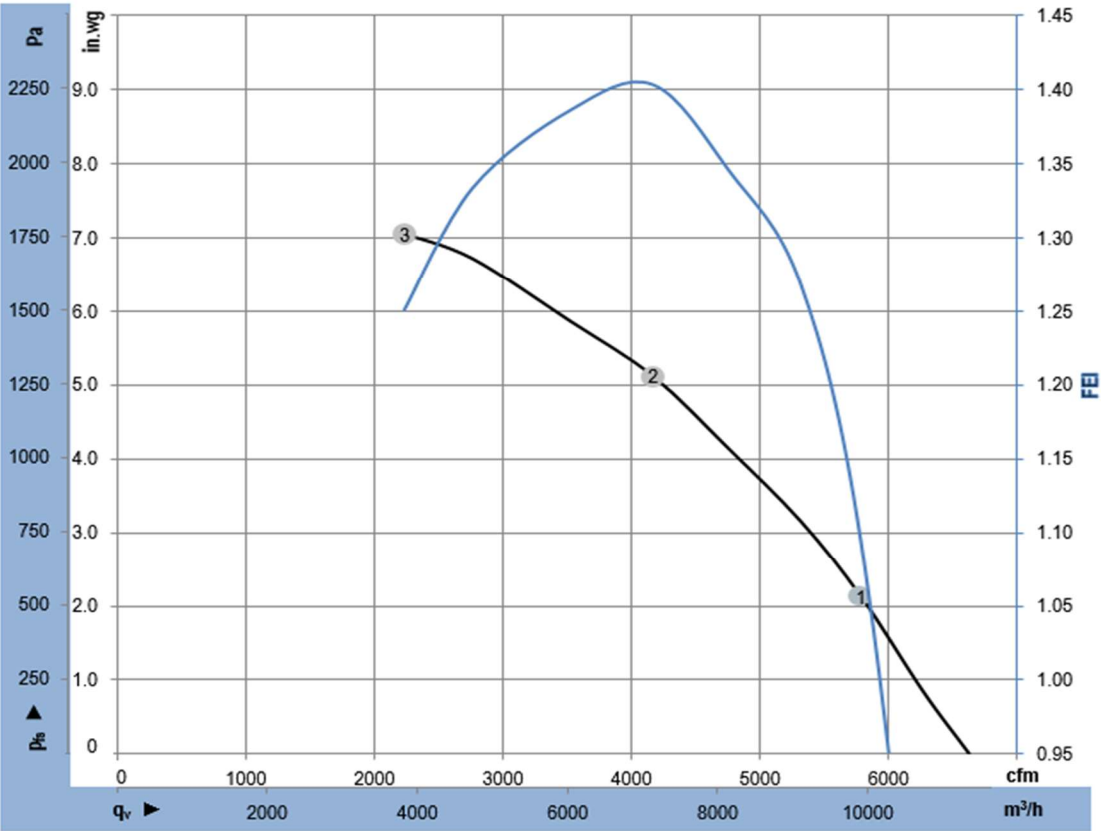
1	Inlet ring with pressure tap K-factor (m³/h & Pa): 188 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79400-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00401-2-2957 (not included in scope of delivery)

Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

[illegible]



$\rho = 0.075 \text{ lbm/ft}^3$
Measurement: LU-1799
ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	2797	3231	4.4	5787	2.1	1.09
2	3~	460	60	2801	3950	5.3	4168	5.1	1.40
3	3~	460	60	2801	3408	4.6	2239	7.0	1.25

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R240450A	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2290
Power consumption	W	3924
Current draw	A	10.4
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

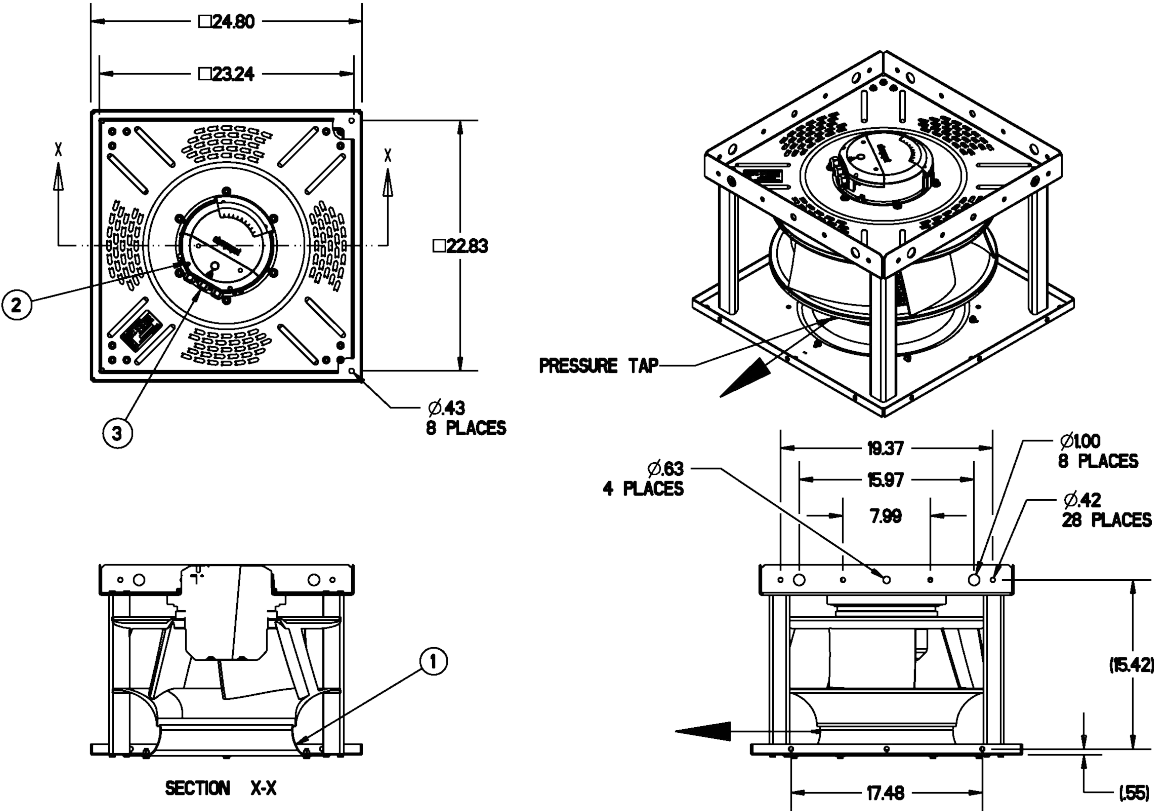
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	97 lb (44 kg)
Nominal Impeller Size	17.7 in (450 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

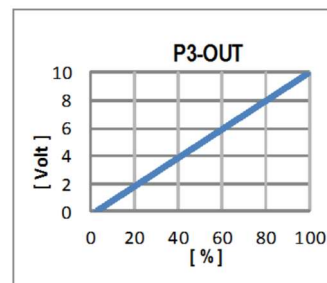
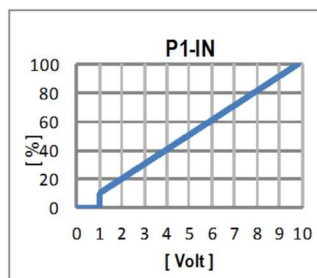
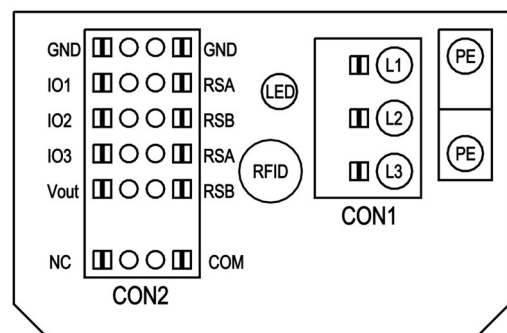
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 240 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface



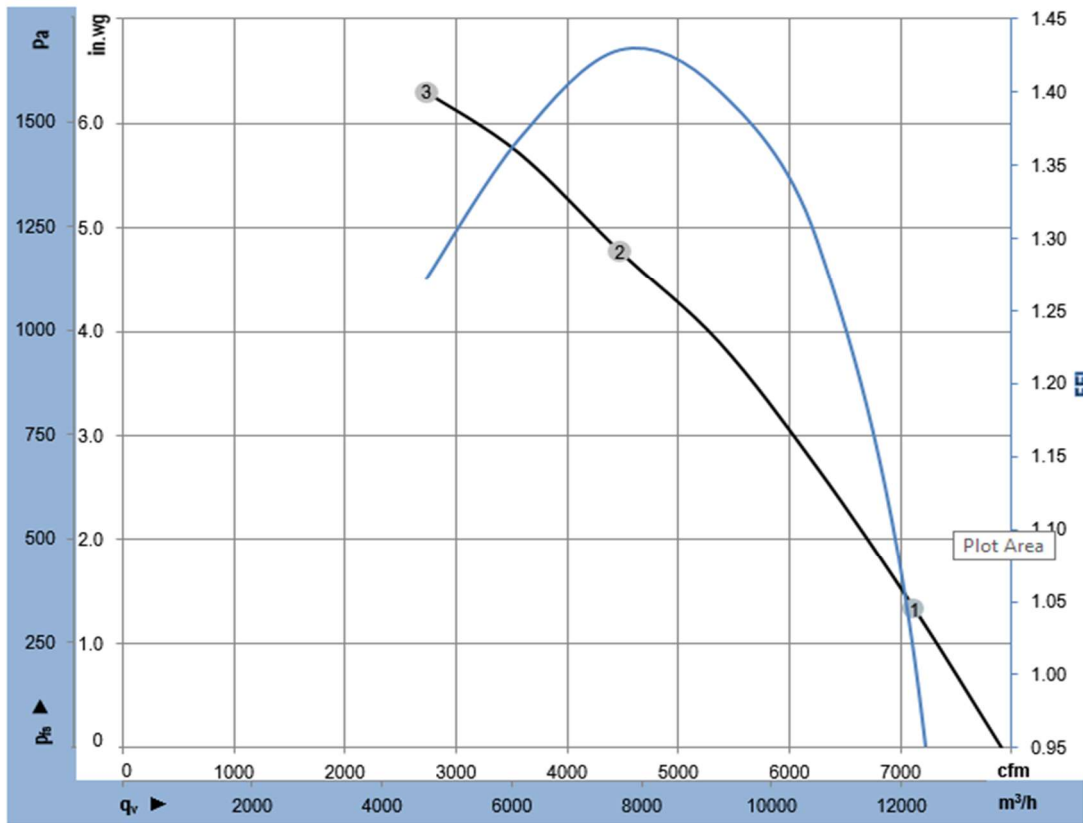
No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 V / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 V, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

Terminal assignment

CON2	configurable IO mode	electrical specification	configurable IO functions: normal / inverse	MODBUS Register for IO mode configuration	D158 [0]	D158 [2]	D158 [5]	D158 [6]	D159 [0]	D159 [2]	D159 [3]	D15A [0]	D15A [1]	D15A [7]	D15A [8]	D15A [4]	D15A [5]	D15A [6]	D16E [..]
IO1	○ Din1 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC																	
	○ Ain1 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz, SELV$																	
	○ Tacho out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV																	
	○ Diagnostics out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV																	
IO2	○ Din2 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC																	
	○ Ain2 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz, SELV$																	
	○ Ain2 4-20mA: analog input	Ri = 125R, characteristic curve parameterizable, SELV																	
	○ Din3 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC																	
IO3	○ Din3 (active low): digital input	active: applied voltage < 1,5VDC, SELV not active: pin open or applied voltage 3,5-50VDC																	
	○ PWMIn3: digital input idle level high	PWM = 40Hz - 10kHz, characteristics parameterizable active: pin open or applied voltage 3,5-50VDC not active: applied voltage < 1,5VDC, SELV																	
	○ PWMIn3: digital input idle level low	40Hz - 10kHz, characteristics parameterizable active: applied voltage 3,5-50VDC not active: pin open or applied voltage < 1,5VDC, SELV																	
	○ Aout3 0-10V: analog output	function parameterizable, max. 5mA max output frequency 300Hz, SELV																	
RSA RSB	○ Tacho out (pulses), analog output	0-10V max. 5mA, max output frequency 300Hz, SELV																	
	○ Diagnostics out (pulses)	0-10V max. 5mA, max output frequency 300Hz, SELV																	
	○ RSA RSB bus connection,	MODBUS RTU, specification V6.3, SELV																	
	voltage output	voltage parameterizable 3.3...24VDC +/- 5%, Pmax=800mW, short-circuit-proof, supply for external devices, SELV																	
Vout	alternatively: Input auxiliary power supply for parameterization via RS485/MODBUS RTU without line voltage	15...50VDC																	

○ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.3



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-1880

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	2299	2965	7.9	7130	1.3	1.01
2	3~	230	60	2274	3893	10.3	4476	4.8	1.43
3	3~	230	60	2300	3604	9.6	2735	6.3	1.27

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480450A	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2440
Power consumption	W	4607
Current draw	A	6.2
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

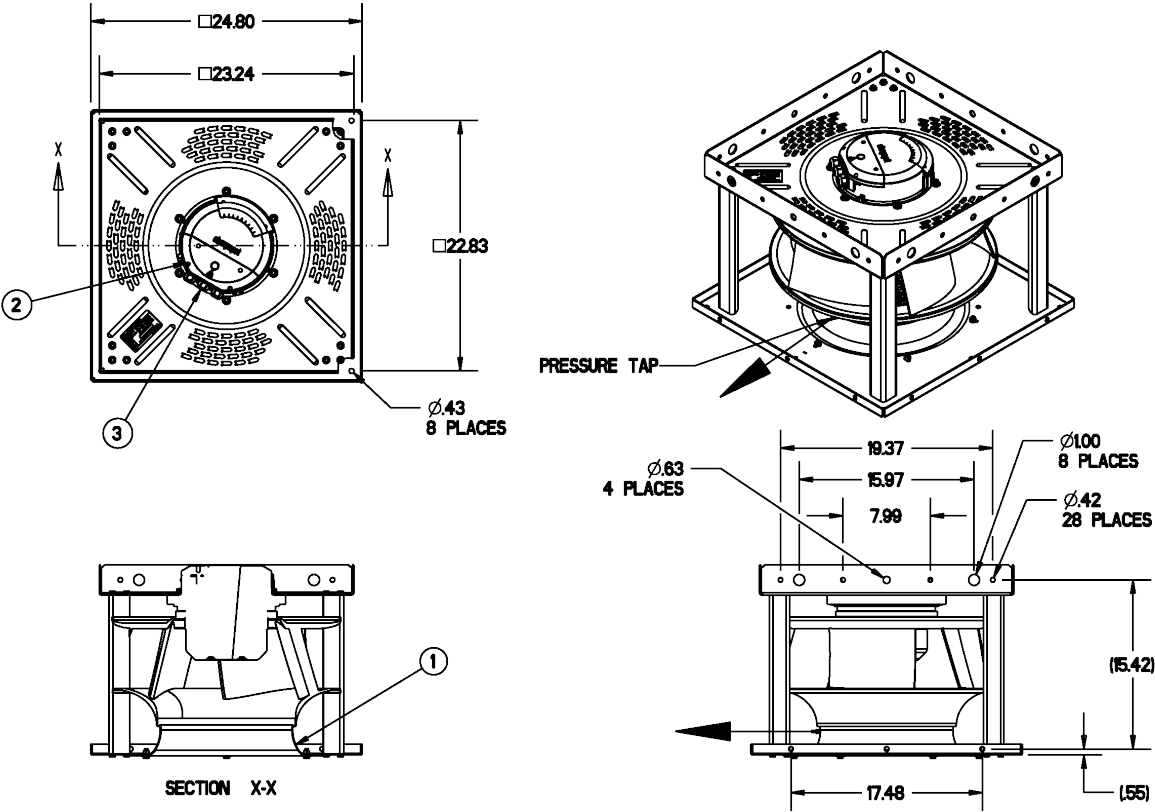
ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description	
Weight	99 lb (45 kg)
Nominal Impeller Size	17.7 in (450 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

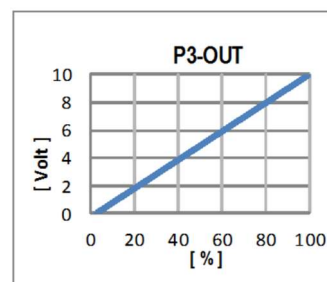
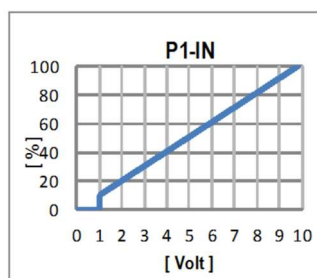
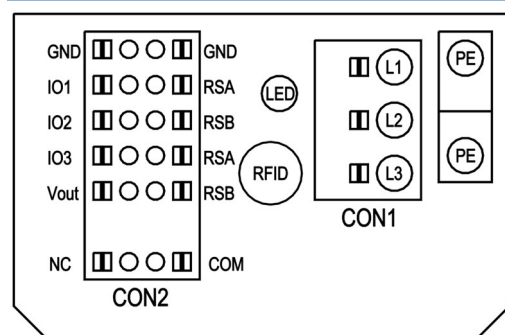
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 240 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface



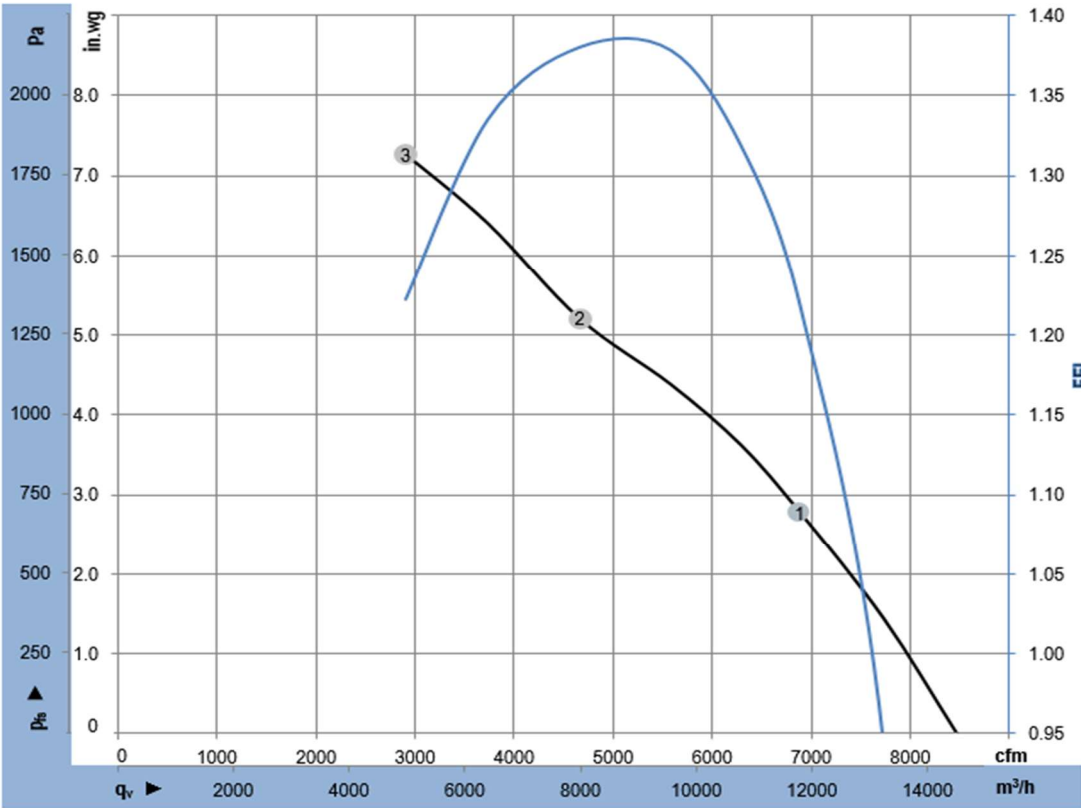
No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

Terminal assignment

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○ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.3



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-1870

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Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	2481	4250	5.7	6889	2.8	1.22
2	3~	460	60	2391	4521	6.2	4664	5.2	1.38
3	3~	460	60	2481	4509	6.0	2909	7.3	1.22

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R240450C	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2600
Power consumption	W	5893
Current draw	A	15.6
Min. ambient temp	°F (°C)	-13 (-25)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

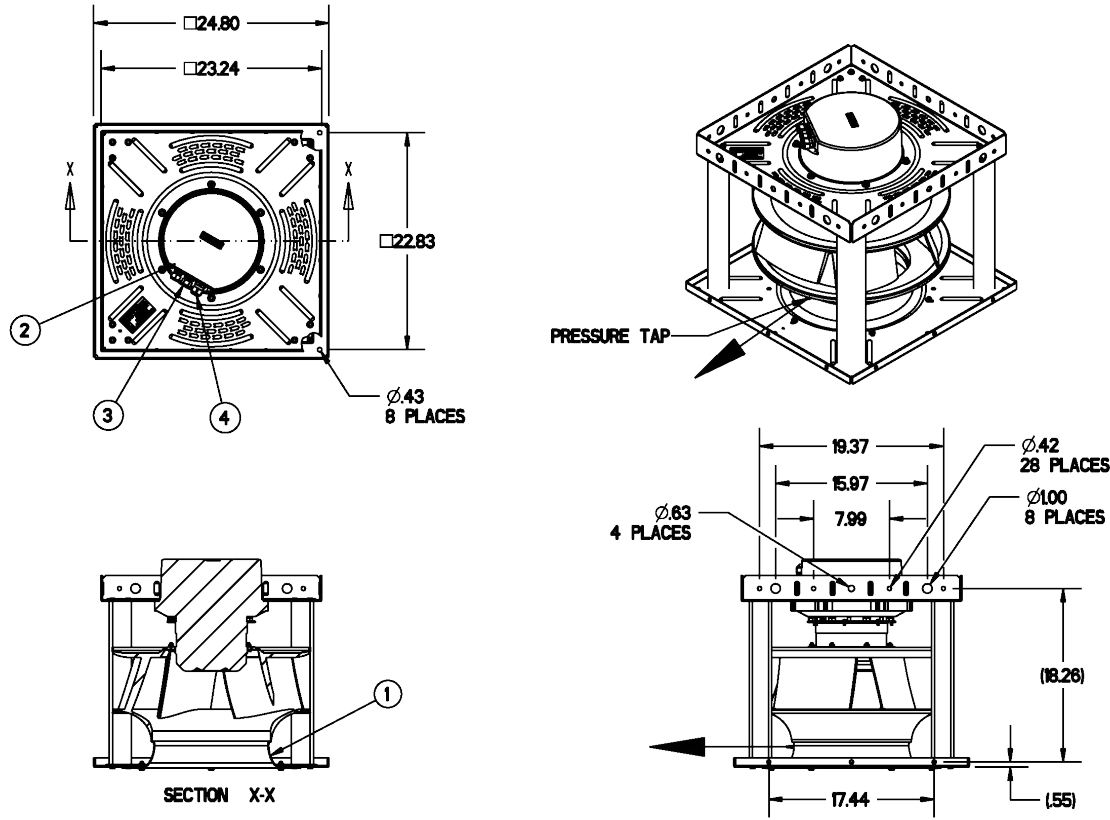
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	126 lb (57.2 kg)
Nominal Impeller Size	17.7 in (450 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 VDC - Input for sensor 0-10 VDC or 4-20 mA - External 24 VDC input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

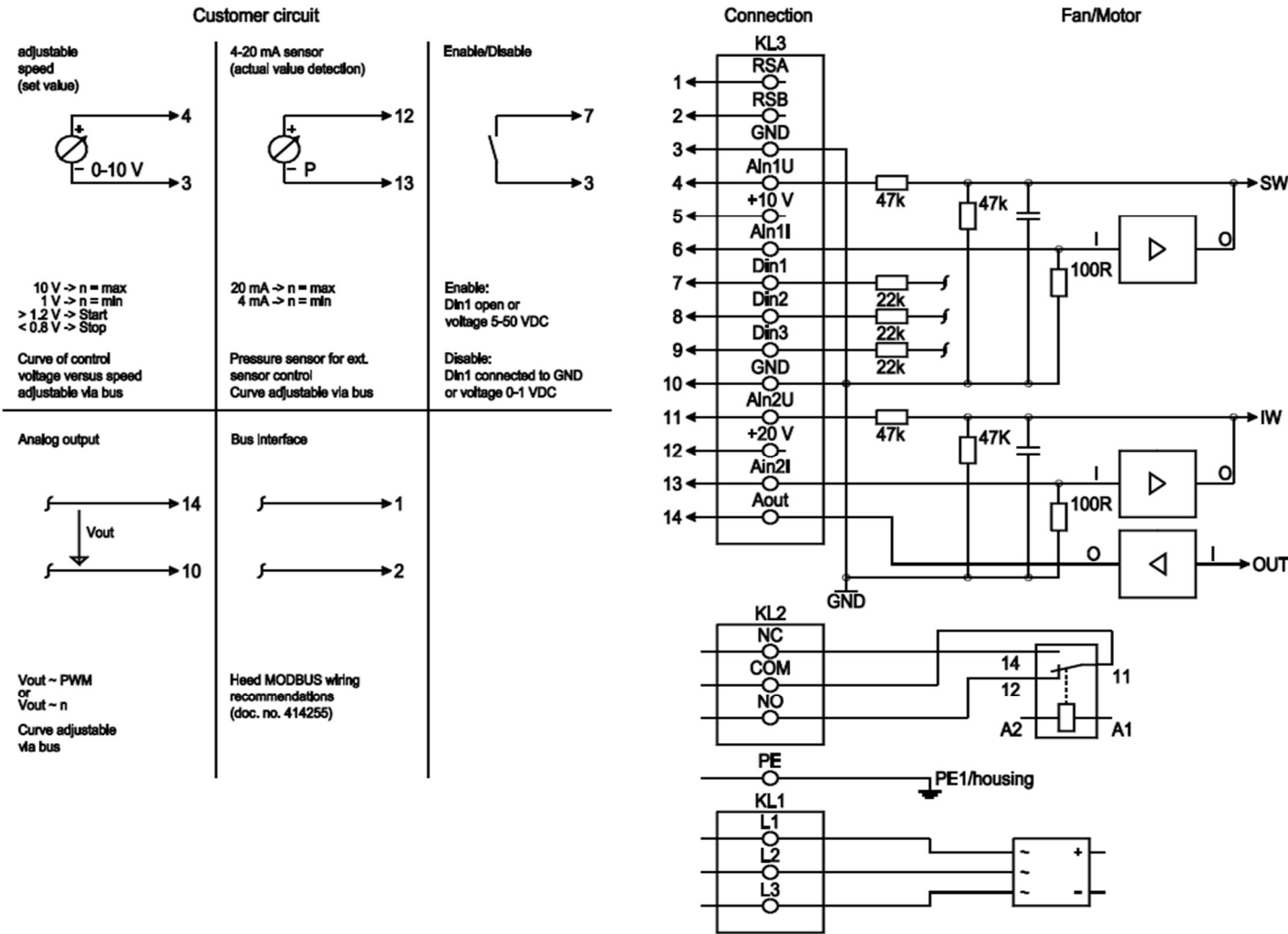
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 240 (available on some variations)
2	Terminal cover tightening torque: 30.9± 4.4 in-lbs (3.5±0.5 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm)
4	Cable diameter: 0.35-0.62 in (9-16 mm) Cable gland tightening torque: 53.1±7.9 in-lbs (6±0.9 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface

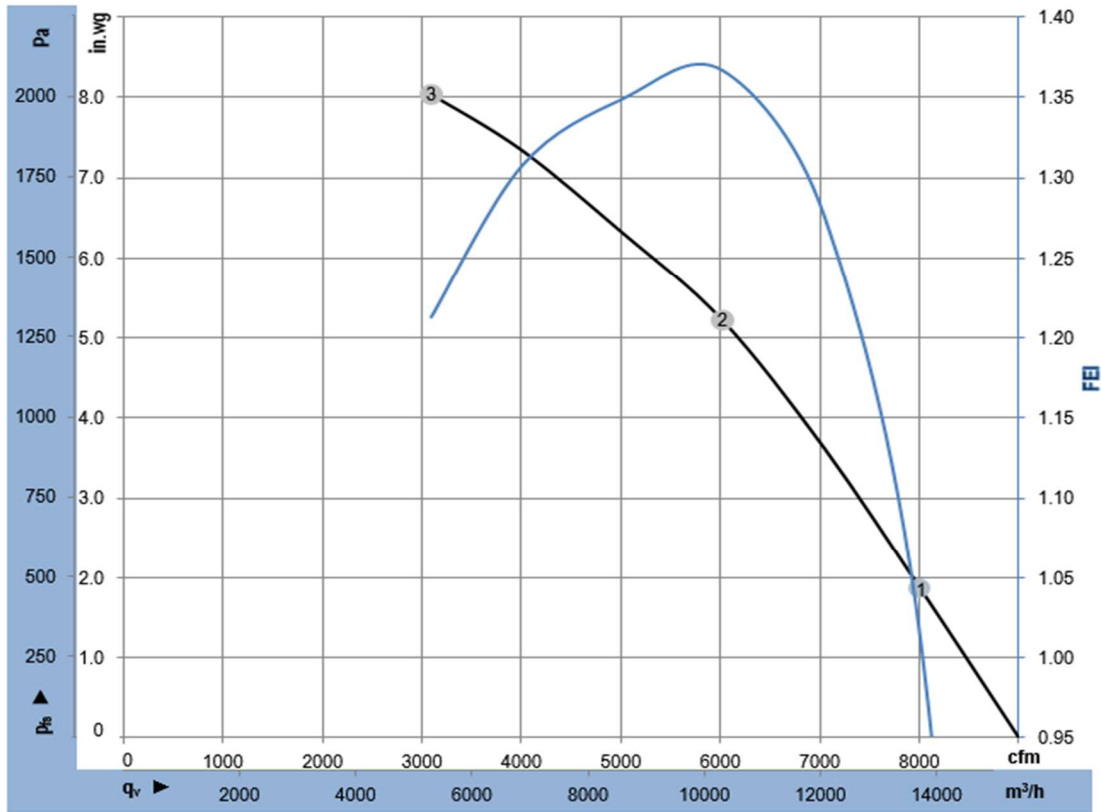


Terminal assignment

Terminal box connection diagram



No.	Conn.	Designation	Function/Assignment
KL1	1,2,3	L1, L2, L3	Power supply, phase, see nameplate for voltage range
PE	PE	PE	Protective earth
KL2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL3	1	RSA	Bus connection RS485, RSA, MODBUS RTU; SELV
KL3	2	RSB	Bus connection RS485, RSB, MODBUS RTU; SELV
KL3	3/10	GND	Reference ground for control interface; SELV
KL3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ± 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL3 KL3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV
KL3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL3	9	Din3	Digital input 3: Direction of action of integrated controller, according to EEPROM setting, the direction of action of the integrated controller can be selected as normal/inverse via bus or digital input Normal: Pin open or applied voltage 5-50 VDC Inverse: Bridge to GND or applied voltage < 1 VDC; SELV
KL3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ± 25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level; adjustable curve; SELV



$\rho = 0.075 \text{ lbm/ft}^3$
Measurement: LU-1890
ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	2599	4251	11.4	8025	1.8	1.01
2	3~	230	60	2601	5796	15.4	6023	5.2	1.37
3	3~	230	60	2601	5268	13.9	3097	8.0	1.21

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480450C	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2600
Power consumption	W	5851
Current draw	A	7.8
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

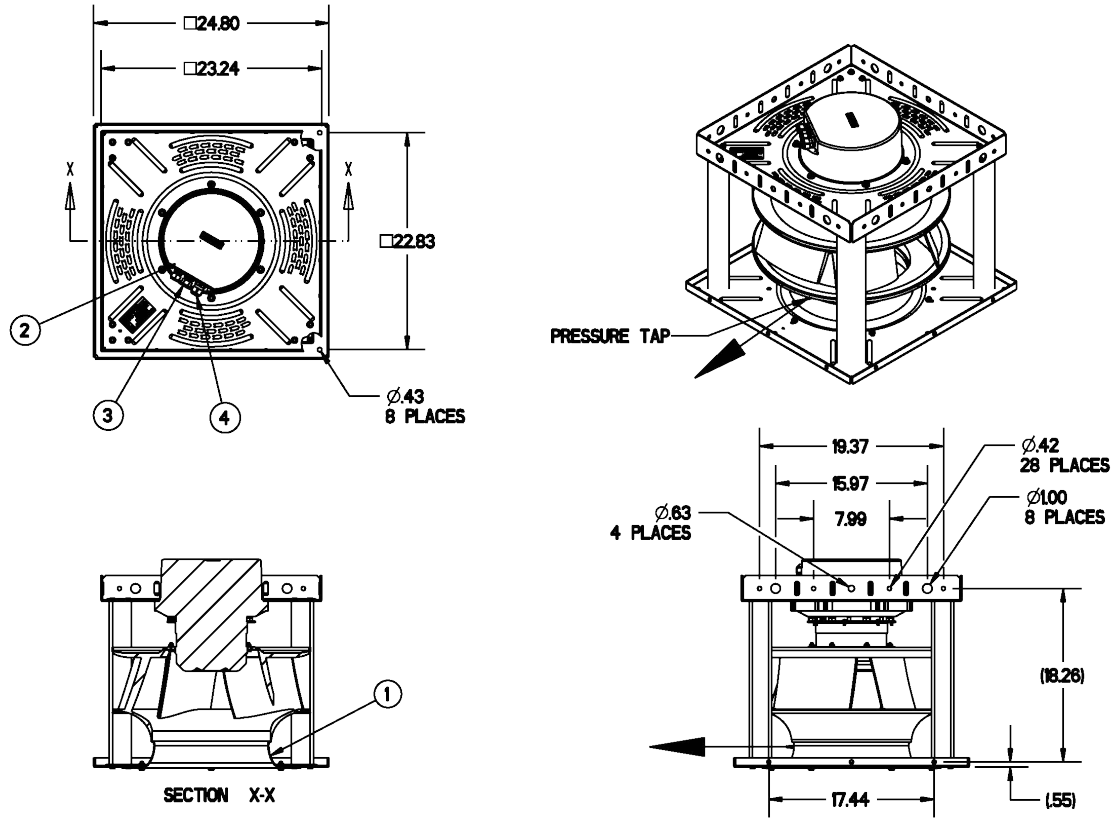
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	126 lb (57.2 kg)
Nominal Impeller Size	17.7 in (450 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output for slave 0-10 VDC - External 24 VDC input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Motor protection	Reverse polarity and locked-rotor protection
Electrical hookup	Terminal box
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

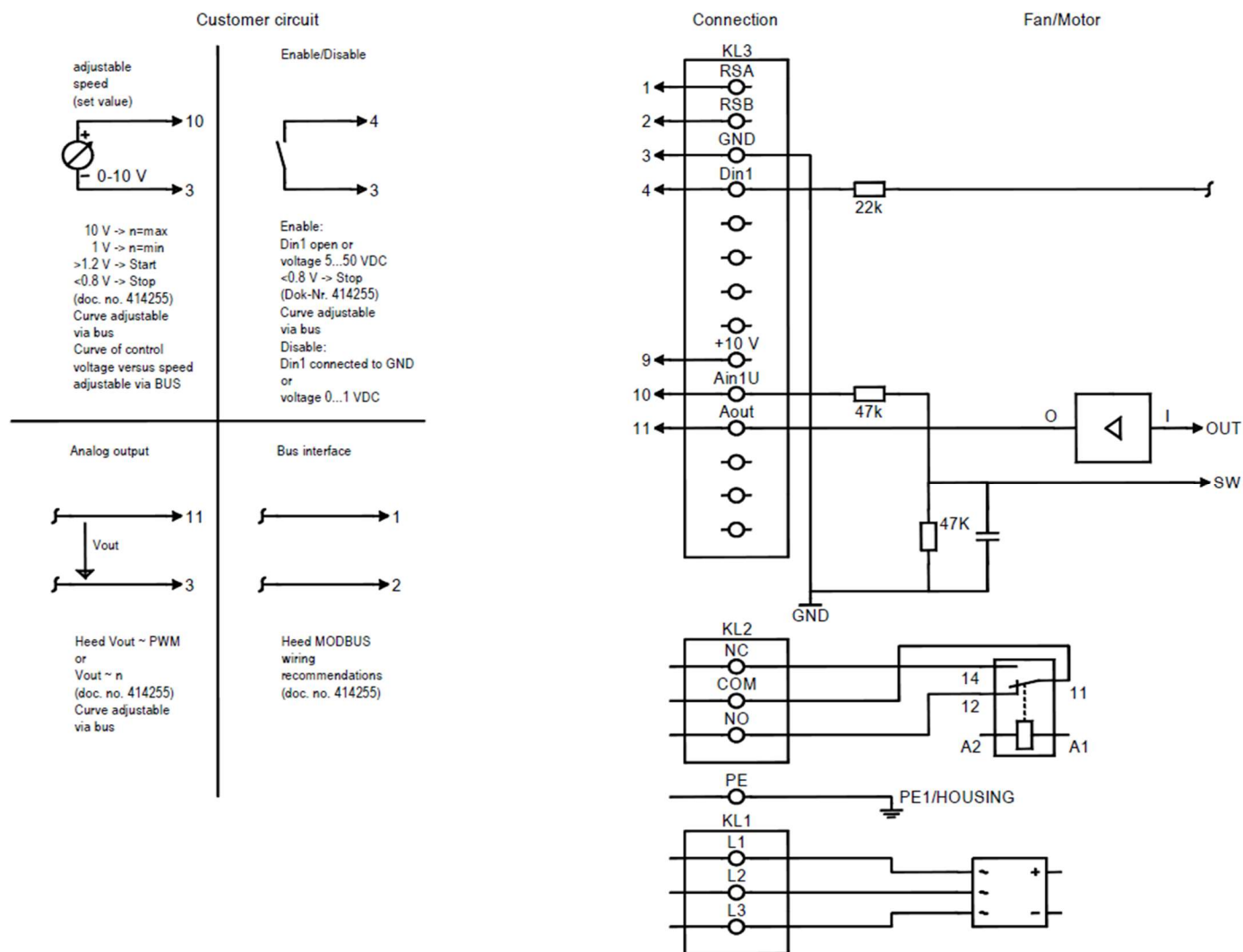
Product drawing

Dimensions in inches



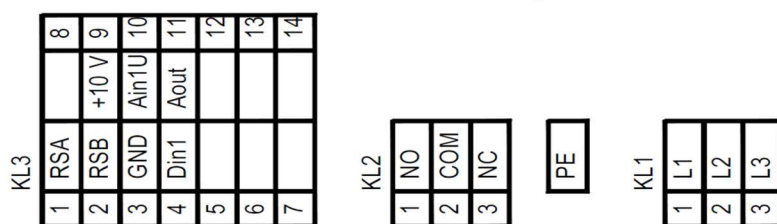
1	Inlet ring with pressure tap K-factor (m³/h & Pa): 240 (available on some variations)
2	Terminal cover tightening torque: 30.9± 4.4 in-lbs (3.5±0.5 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm)
4	Cable diameter: 0.35-0.62 in (9-16 mm) Cable gland tightening torque: 53.1±7.9 in-lbs (6±0.9 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface

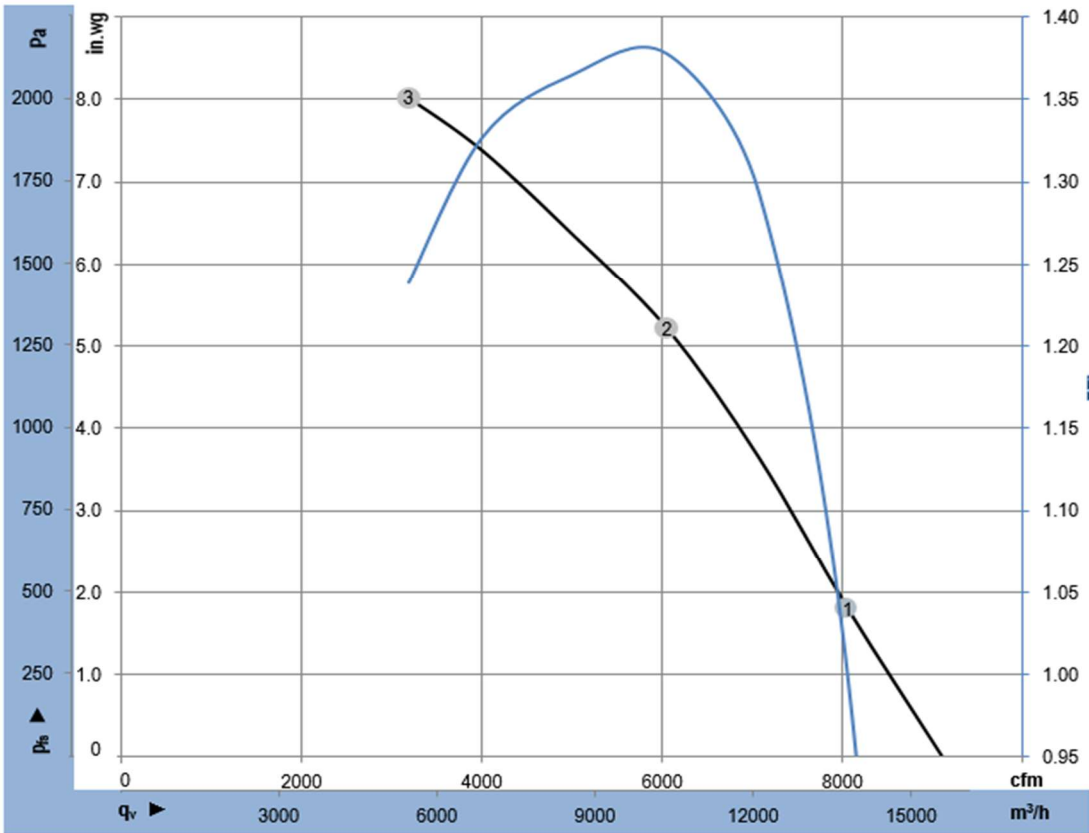


Terminal assignment

Terminal box connection diagram



No.	Conn.	Designation	Function/Assignment
KL1	1,2,3	L1, L2, L3	Power supply, phase, see nameplate for voltage range
PE	PE	PE	Protective earth
KL2	1	NO	Status relay, floating status contact, option 1: make for failure, option 2: make for error for run monitor
KL2	2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; basic insulation on supply side and reinforced insulation on control interface side
KL2	3	NC	Status relay, floating status contact, option 1: break for failure, option 2: break for error message for run monitor
KL3	1	RSA	RS485 interface for MODBUS, RSA; SELV
KL3	2	RSB	RS485 interface for MODBUS, RSB; SELV
KL3	3	GND	Reference ground for control interface; SELV
KL3	4	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-
KL3	9	+10 V	Voltage output 10 V/max. 10 mA, power supply for external devices (e.g. potentiometers), SELV
KL3	10	Ain1U	Analog input 1, set value: 0-10 VDC, Ri = 100 kΩ, adjustable curve; SELV
KL3	11	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-1902

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	2599	4218	5.7	8061	1.8	1.00
2	3~	460	60	2600	5772	7.7	6054	5.2	1.38
3	3~	460	60	2600	5287	7.1	3189	8.0	1.24

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R240500A	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	1930
Power consumption	W	3911
Current draw	A	10.4
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

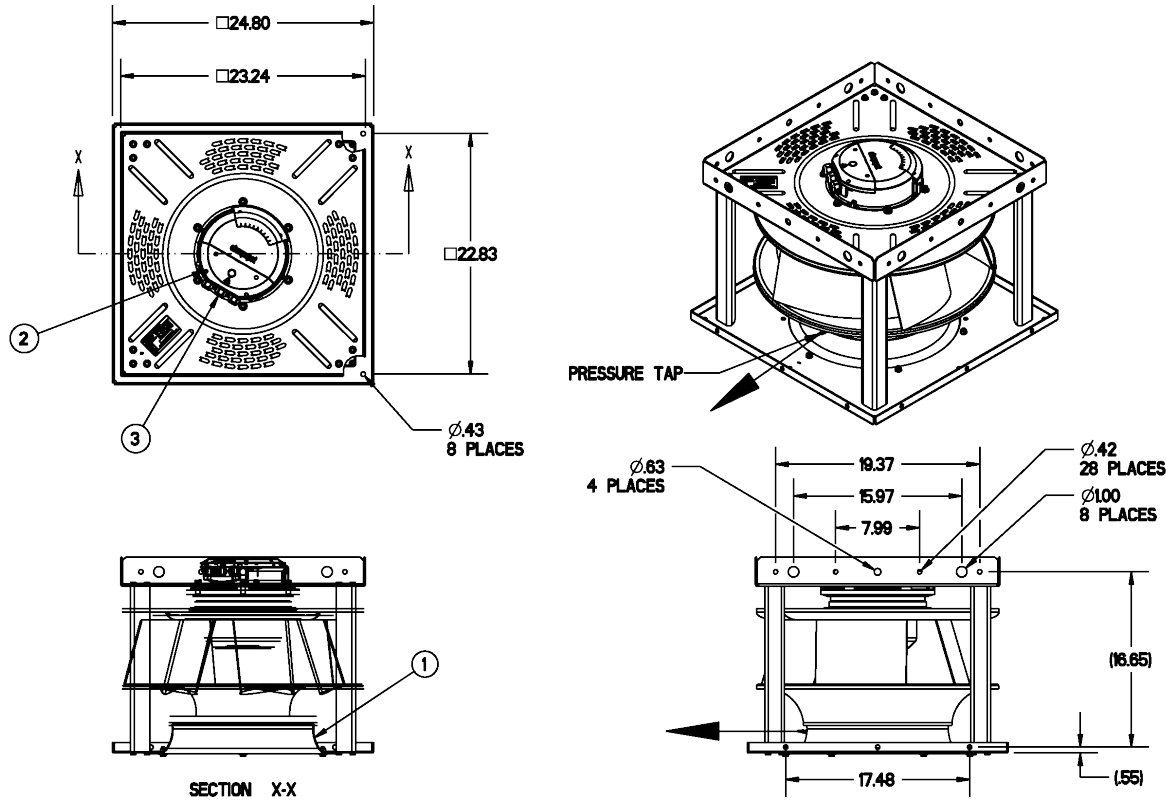
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	110 lb (49.9 kg)
Nominal Impeller Size	19.7 in (500 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

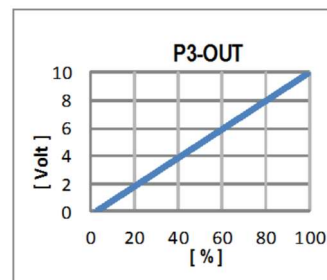
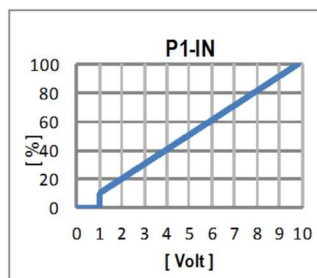
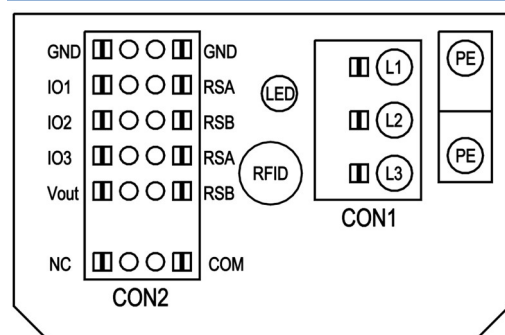
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 281 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 V / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 V, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

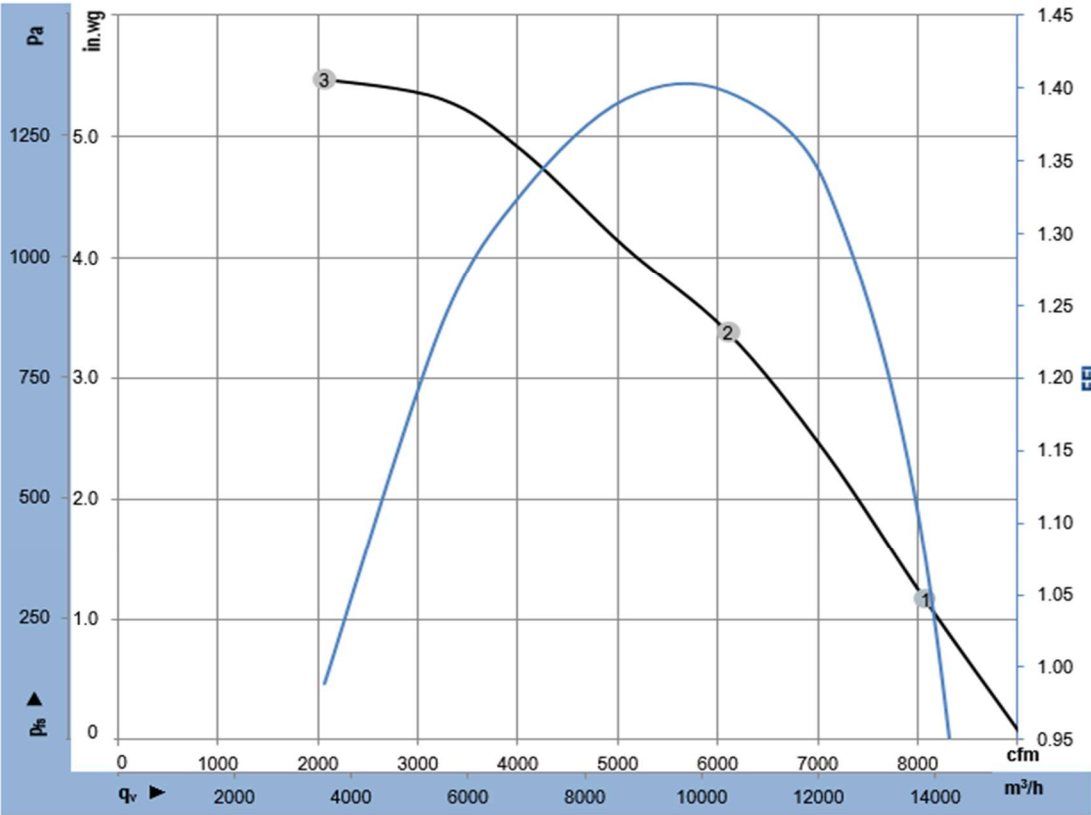
Terminal assignment

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o configurable option

For further information and additional functions see EC Control Software, Fan-Set-App,
or MODBUS Parameter Specification V6.3

CON2	configurable IO mode	electrical specification	configurable IO functions: normal / inverse
IO1	o Din1 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D158 [0]
	o Ain1 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV	D158 [2]
	o Tach out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV	D158 [5]
	o Diagnostics out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV	D158 [6]
IO2	o Din2 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D159 [0]
	o Ain2 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV	D159 [2]
	o Ain2 4-20mA: analog input	Ri = 125R, characteristic curve parameterizable, SELV	D159 [3]
	o Din3 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D15A [0]
IO3	o Din3 (active low): digital input	active: applied voltage < 1,5VDC, SELV not active: pin open or applied voltage 3,5-50VDC	D15A [1]
	o PWM in3: digital input idle level high	PWM = 40Hz - 10kHz, characteristics parameterizable active: pin open or applied voltage 3,5-50VDC not active: applied voltage < 1,5VDC, SELV	D15A [7]
	o PWM in3: digital input idle level low	40Hz - 10kHz, characteristics parameterizable active: applied voltage 3,5-50VDC not active: pin open or applied voltage < 1,5VDC, SELV	D15A [8]
	o Aout3 0-10V: analog output	function parameterizable, max. 5mA max output frequency 300Hz, SELV	D15A [4]
	o Tacho out (pulses), analog output	0-10V max. 5mA, max output frequency 300Hz, SELV	D15A [5]
	o Diagnostics out (pulses)	0-10V max. 5mA max output frequency 300Hz, SELV	D15A [6]
RSA RSB	RS485 bus connection,	MODBUS RTU, specification V6.3, SELV	
Vout	voltage output	voltage parameterizable 3,3...24VDC +/- 5%, Pmax=800mW, short-circuit-proof, supply for external devices, SELV	D16E [...]
	alternatively: input auxiliary power supply for parameterization via RS485/MODBUS RTU without line voltage	15...50VDC	



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-1987

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	1936	2825	7.6	8085	1.2	1.07
2	3~	230	60	1934	3911	10.4	6102	3.4	1.40
3	3~	230	60	1936	3215	8.6	2068	5.5	0.99

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480500A	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2000
Power consumption	W	4177
Current draw	A	5.6
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	113 (45)

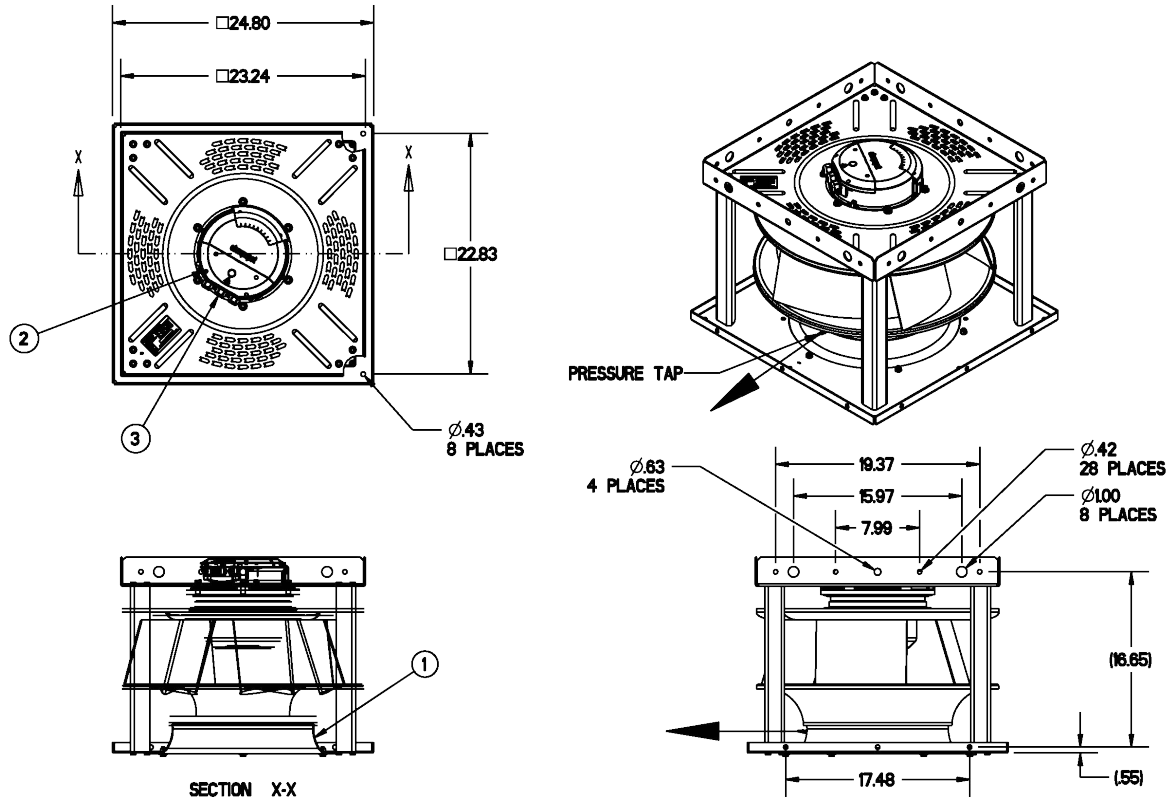
ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description	
Weight	110 lb (49.9 kg)
Nominal Impeller Size	19.7 in (500 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

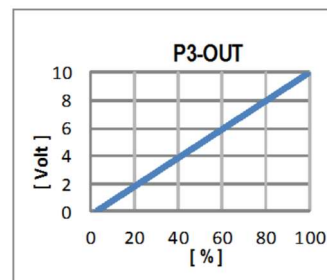
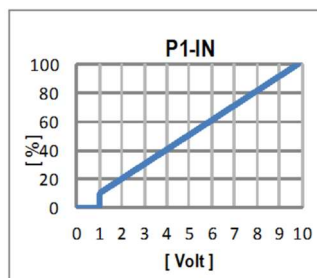
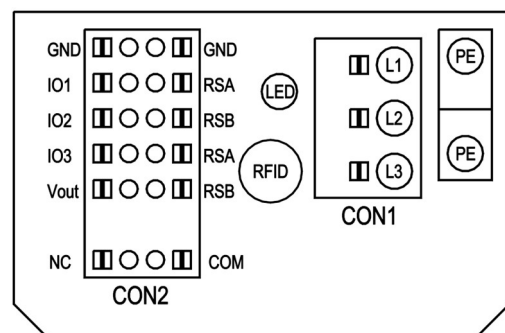
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 281 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

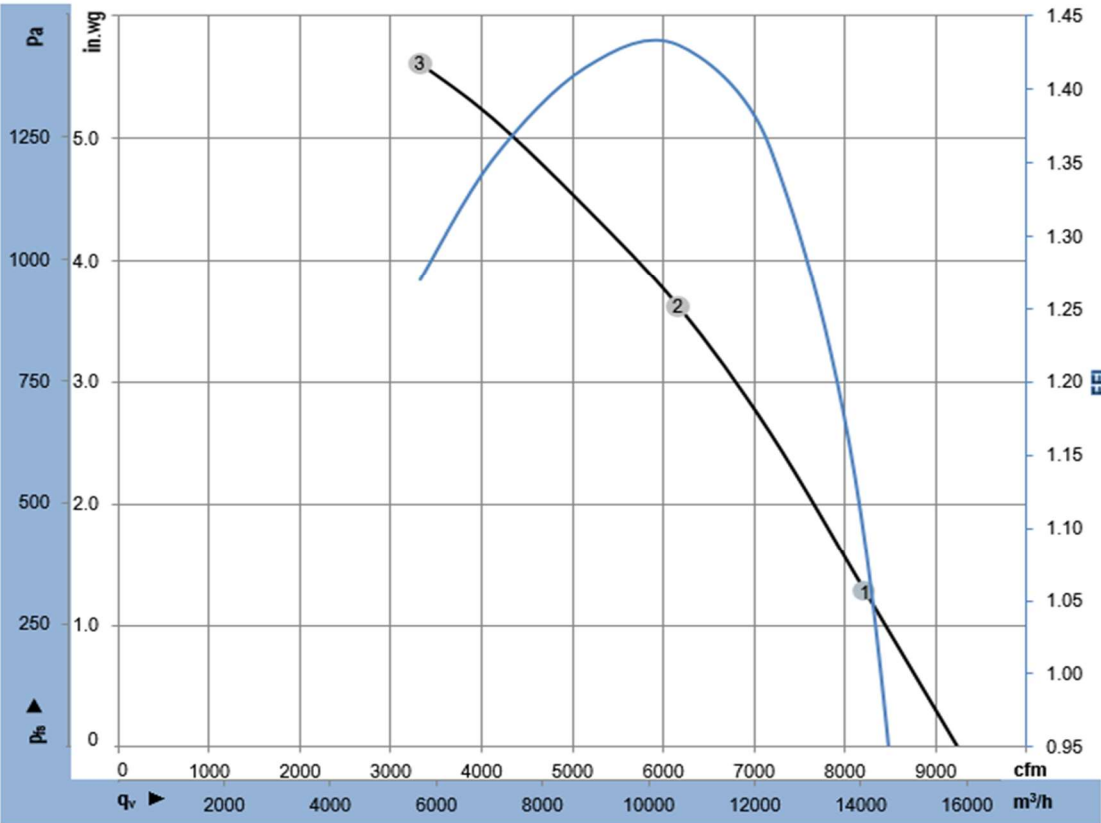
Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

[illegible]

ebm papst



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-2072

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	1996	3033	4.1	8226	1.3	1.09
2	3~	460	60	1996	4091	5.5	6161	3.6	1.43
3	3~	460	60	2000	3860	5.2	3319	5.6	1.27

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R240500C	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2250
Power consumption	W	6297
Current draw	A	16.8
Min. ambient temp	°F (°C)	-13 (-25)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

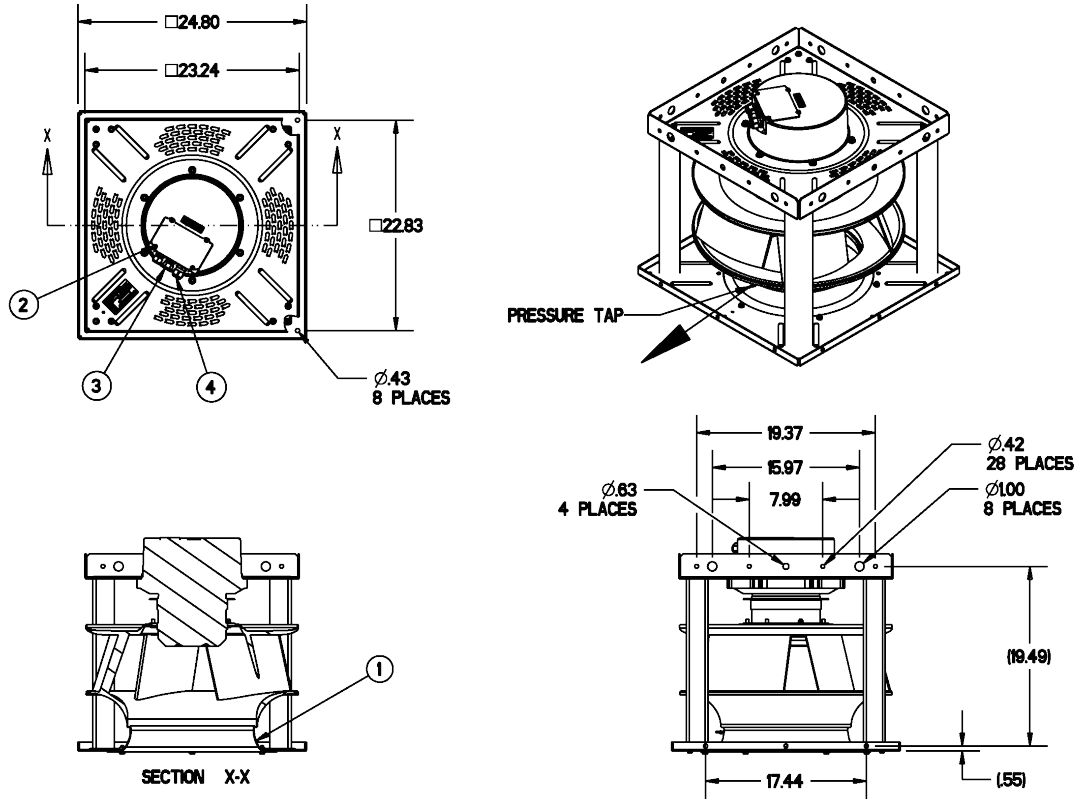
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	132 lb (59.9 kg)
Nominal Impeller Size	19.7 in (500 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 VDC - Input for sensor 0-10 VDC or 4-20 mA - External 24 VDC input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

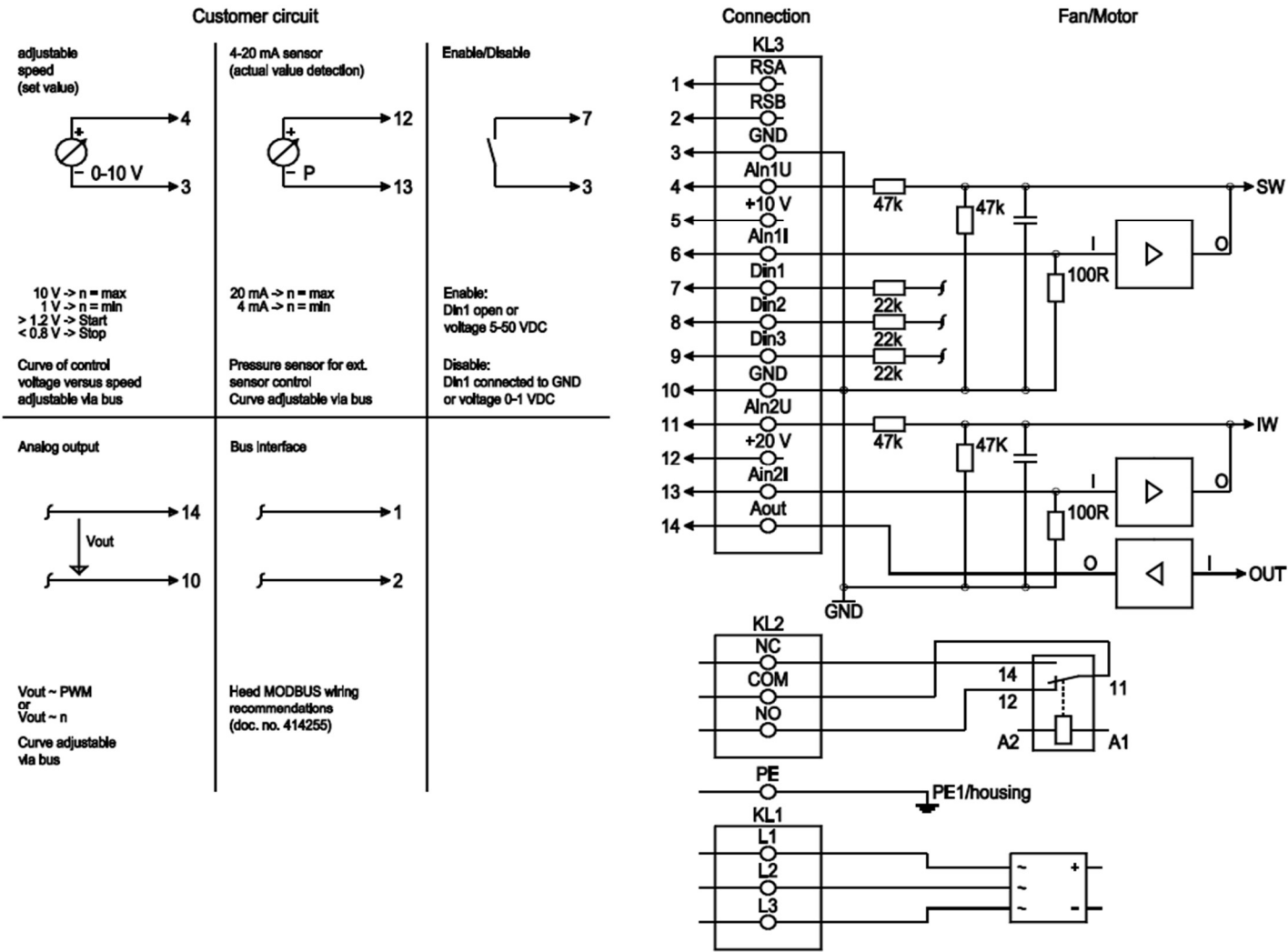
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 281 (available on some variations)
2	Terminal cover tightening torque: 30.9± 4.4 in-lbs (3.5±0.5 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm)
4	Cable diameter: 0.35-0.62 in (9-16 mm) Cable gland tightening torque: 53.1±7.9 in-lbs (6±0.9 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface

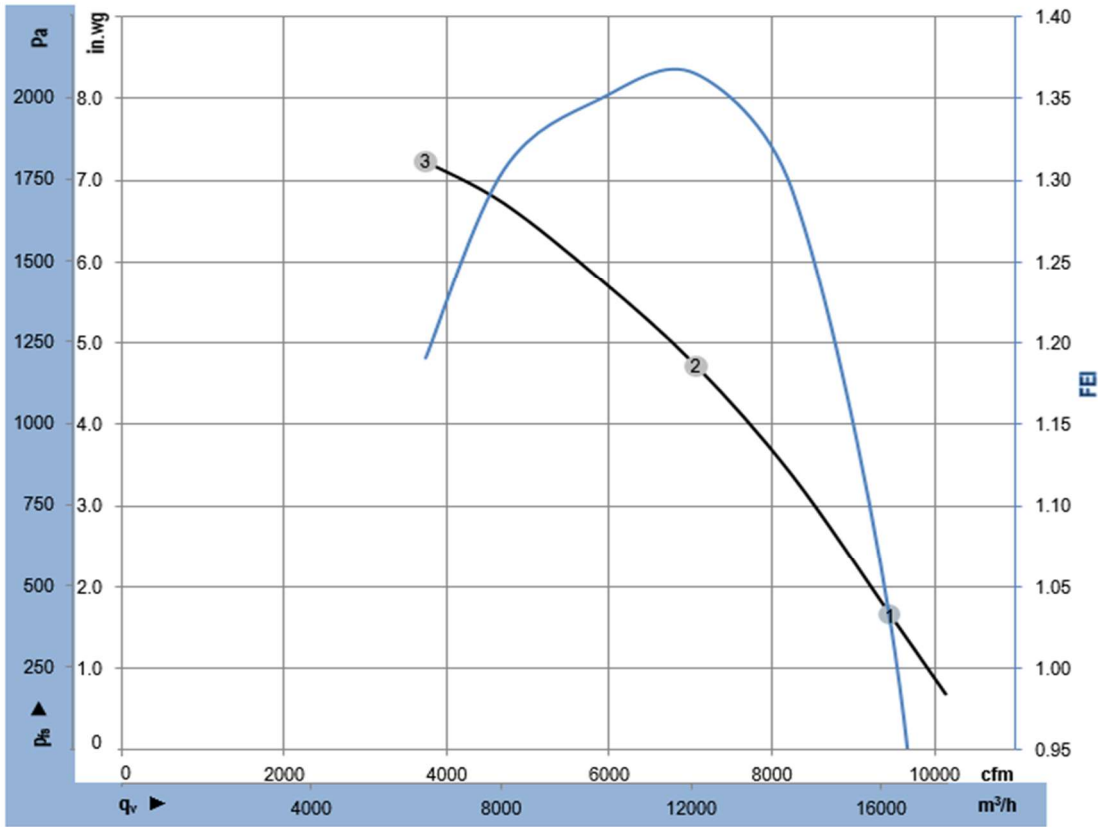


Terminal assignment

Terminal box connection diagram



No.	Conn.	Designation	Function/Assignment
KL1	1,2,3	L1, L2, L3	Power supply, phase, see nameplate for voltage range
PE	PE	PE	Protective earth
KL2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL3	1	RSA	Bus connection RS485, RSA, MODBUS RTU; SELV
KL3	2	RSB	Bus connection RS485, RSB, MODBUS RTU; SELV
KL3	3/10	GND	Reference ground for control interface; SELV
KL3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ± 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL3 KL3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV
KL3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL3	9	Din3	Digital input 3: Direction of action of integrated controller, according to EEPROM setting, the direction of action of the integrated controller can be selected as normal/inverse via bus or digital input Normal: Pin open or applied voltage 5-50 VDC Inverse: Bridge to GND or applied voltage < 1 VDC; SELV
KL3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ± 25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level; adjustable curve; SELV



$\rho = 0.075 \text{ lbm/ft}^3$
Measurement: LU-2077

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Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	2251	4439	11.8	9456	1.6	1.03
2	3~	230	60	2248	6147	16.3	7061	4.7	1.36
3	3~	230	60	2248	5765	15.3	3737	7.2	1.19

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480500C	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	2255
Power consumption	W	6292
Current draw	A	8.4
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

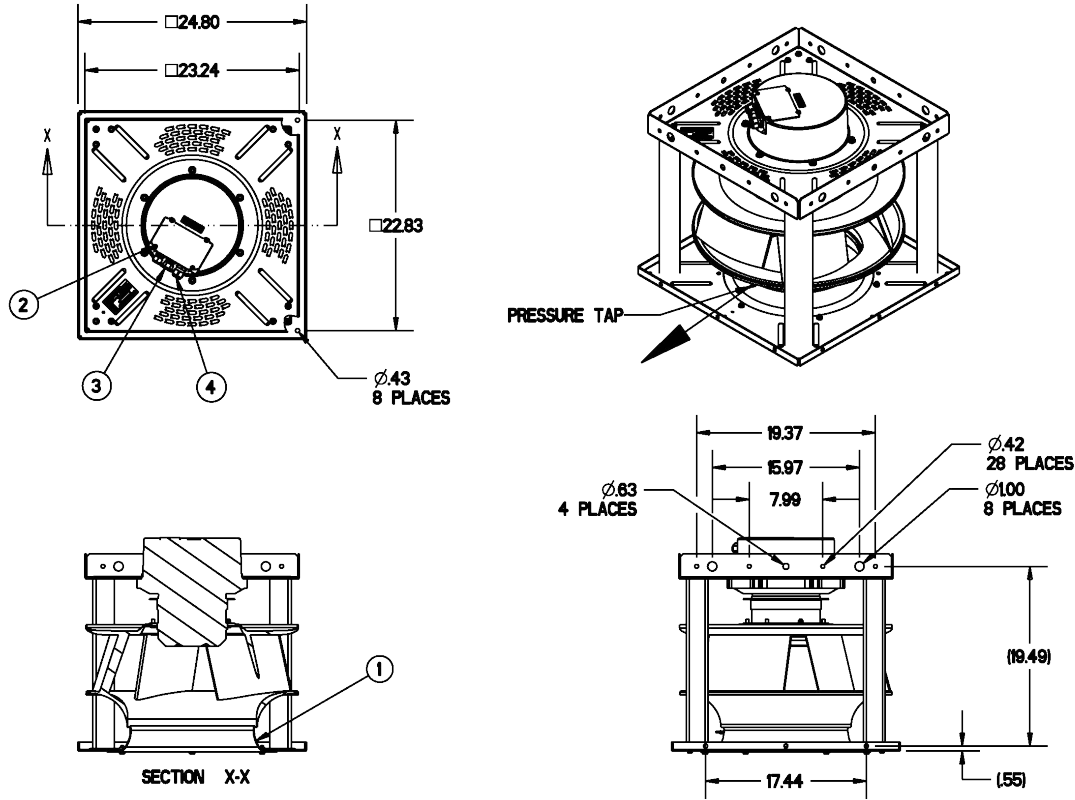
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	132 lb (59.9 kg)
Nominal Impeller Size	19.7 in (500 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output for slave 0-10 VDC - External 24 VDC input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Motor protection	Reverse polarity and locked-rotor protection
Electrical hookup	Terminal box
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

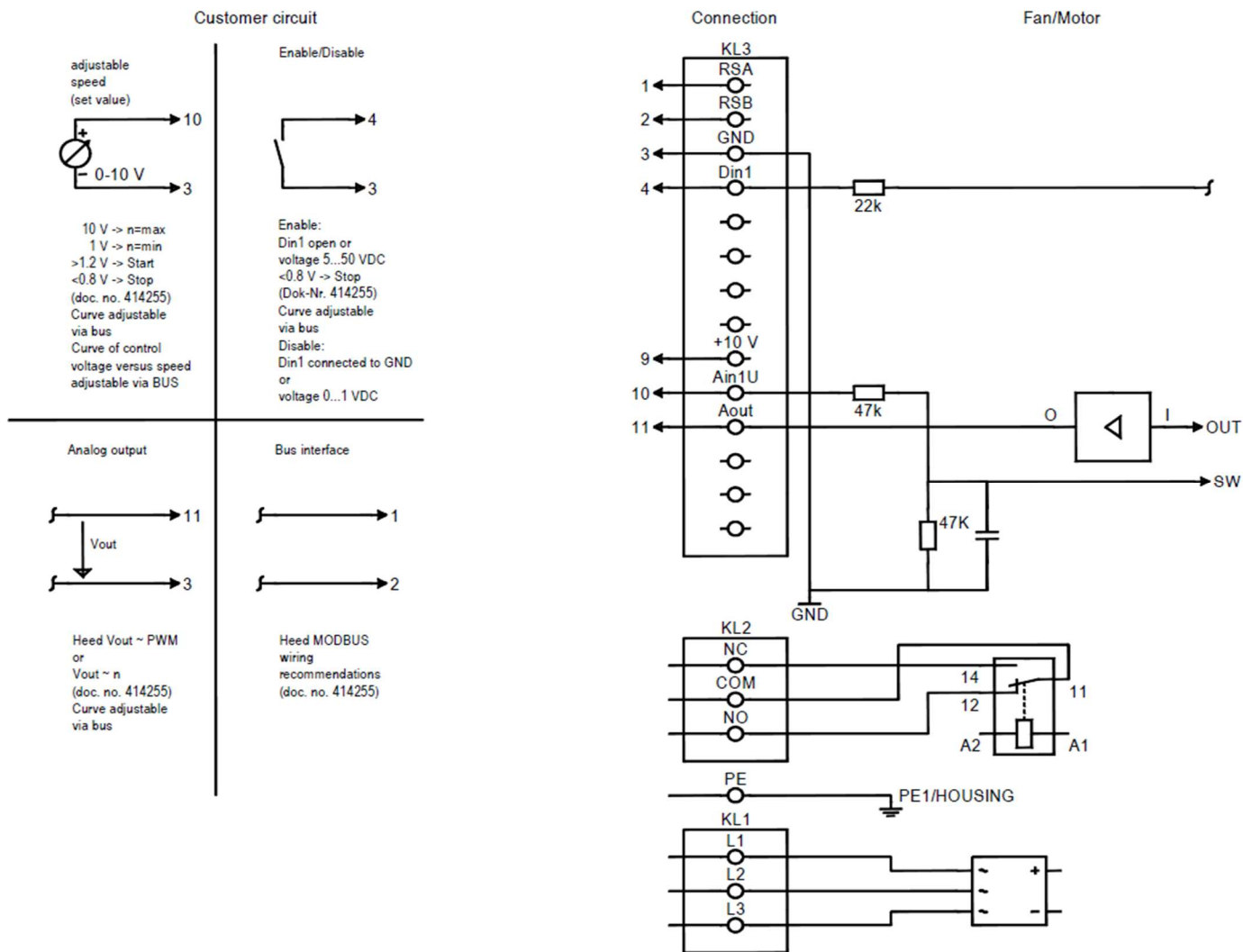
Product drawing

Dimensions in inches



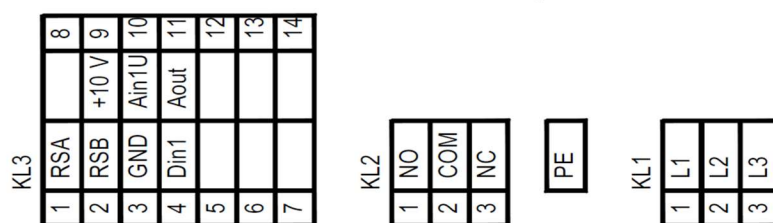
1	Inlet ring with pressure tap K-factor (m³/h & Pa): 281 (available on some variations)
2	Terminal cover tightening torque: 30.9± 4.4 in-lbs (3.5±0.5 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm)
4	Cable diameter: 0.35-0.62 in (9-16 mm) Cable gland tightening torque: 53.1±7.9 in-lbs (6±0.9 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79500-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 35506-2-2957 (not included in scope of delivery)

Electrical Interface

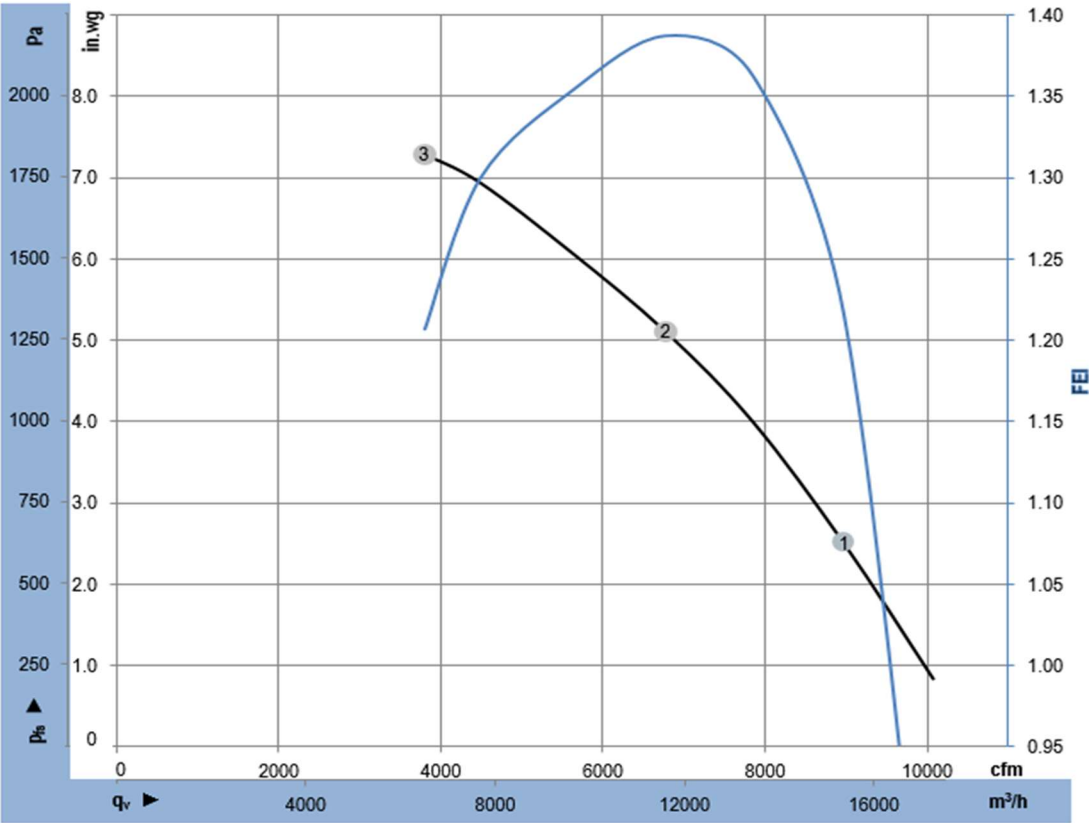


Terminal assignment

Terminal box connection diagram



No.	Conn.	Designation	Function/Assignment
KL1	1,2,3	L1, L2, L3	Power supply, phase, see nameplate for voltage range
PE	PE	PE	Protective earth
KL2	1	NO	Status relay, floating status contact, option 1: make for failure, option 2: make for error for run monitor
KL2	2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; basic insulation on supply side and reinforced insulation on control interface side
KL2	3	NC	Status relay, floating status contact, option 1: break for failure, option 2: break for error message for run monitor
KL3	1	RSA	RS485 interface for MODBUS, RSA; SELV
KL3	2	RSB	RS485 interface for MODBUS, RSB; SELV
KL3	3	GND	Reference ground for control interface; SELV
KL3	4	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-
KL3	9	+10 V	Voltage output 10 V/max. 10 mA, power supply for external devices (e.g. potentiometers), SELV
KL3	10	Ain1U	Analog input 1, set value: 0-10 VDC, Ri = 100 kΩ, adjustable curve; SELV
KL3	11	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-



$\rho = 0.075 \text{ lbm/ft}^3$
Measurement: LU-1940

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Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	2256	5006	6.7	8978	2.5	1.22
2	3~	460	60	2254	6246	8.3	6773	5.1	1.39
3	3~	460	60	2254	5809	7.7	3794	7.3	1.21

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R240560A	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	1585
Power consumption	W	3802
Current draw	A	10.1
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

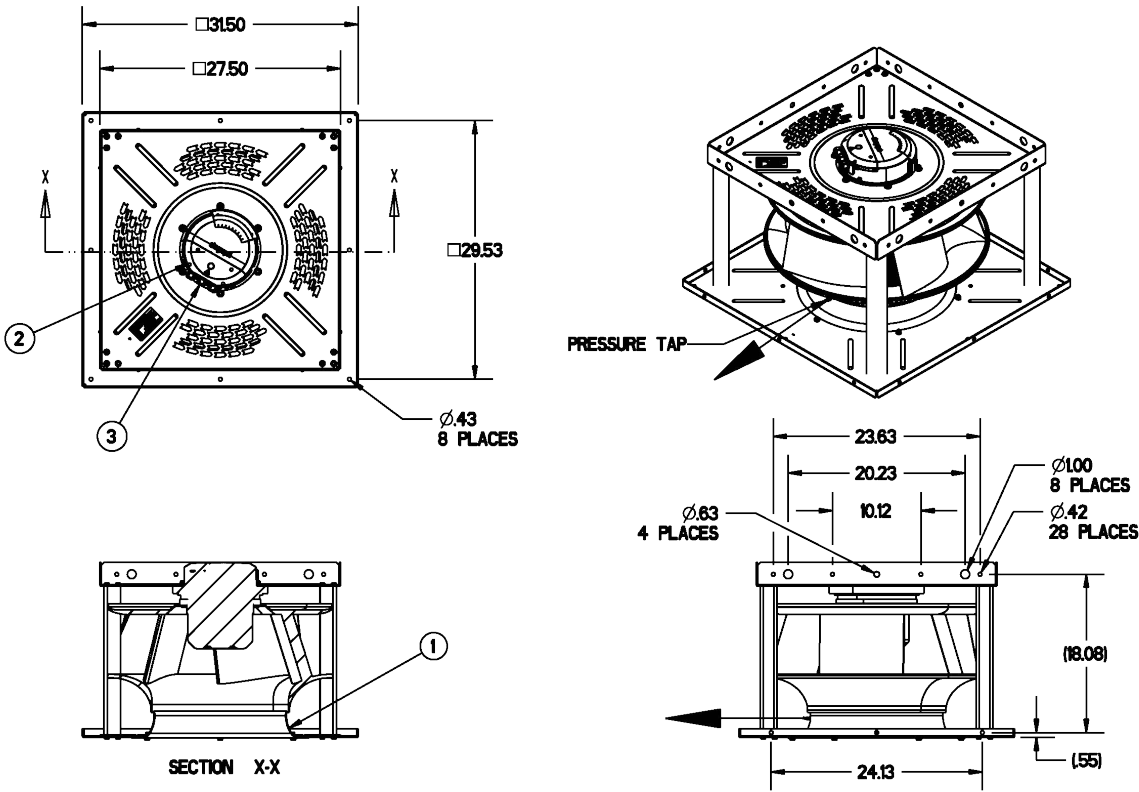
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	140 lb (63.5 kg)
Nominal Impeller Size	22 in (560 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

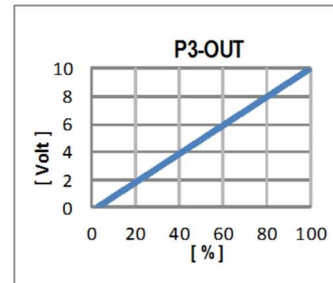
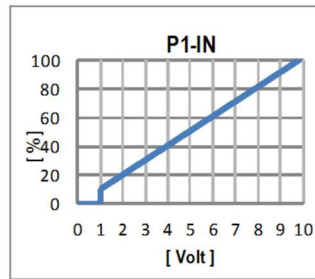
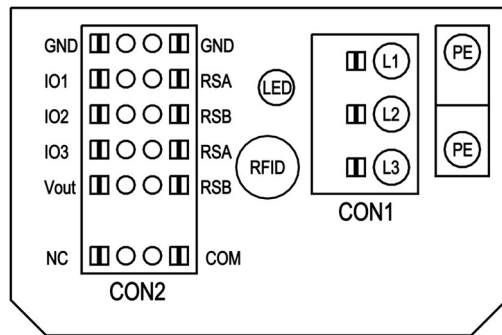
Product drawing

Dimensions in inches

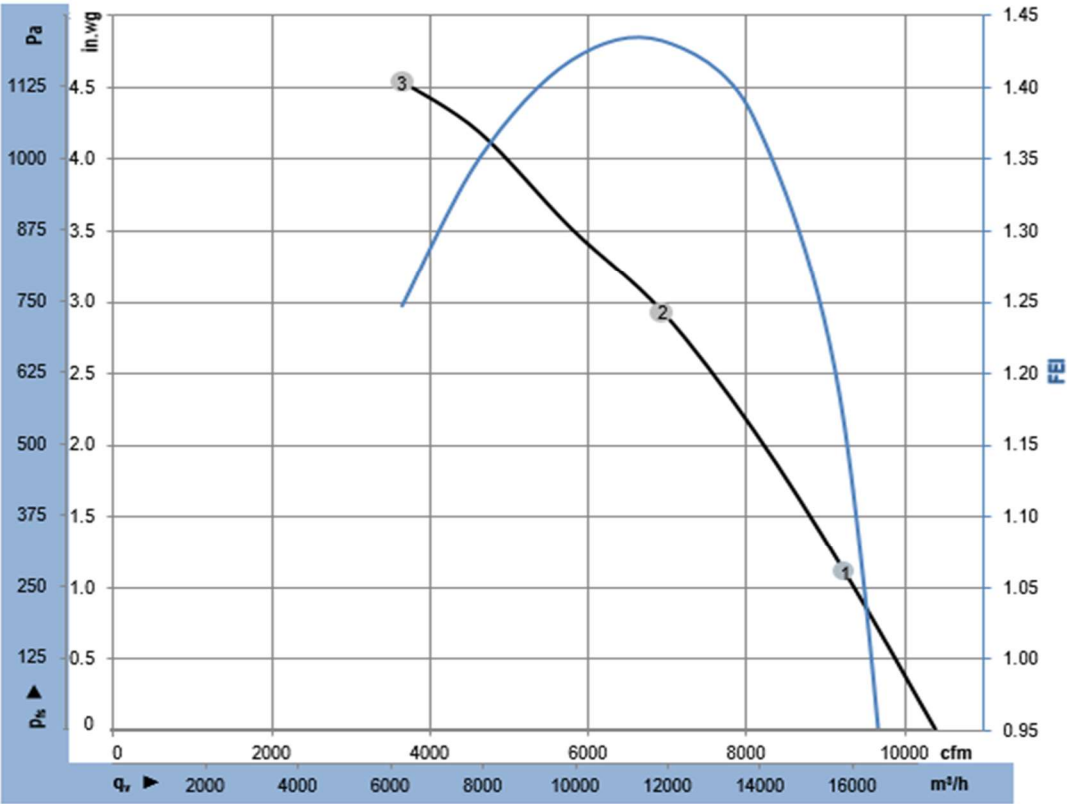


1	Inlet ring with pressure tap K-factor (m³/h & Pa): 348 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79560-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00631-2-2957 (not included in scope of delivery)

Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-2052

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	1588	2870	7.7	9241	1.1	1.16
2	3~	230	60	1586	3802	10.1	6931	2.9	1.43
3	3~	230	60	1587	3535	9.4	3636	4.5	1.25

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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100 Hyde Road
Farmington, CT 06034
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Nominal Data

Model	EG1R480560A	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	1675
Power consumption	W	4494
Current draw	A	6.0
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

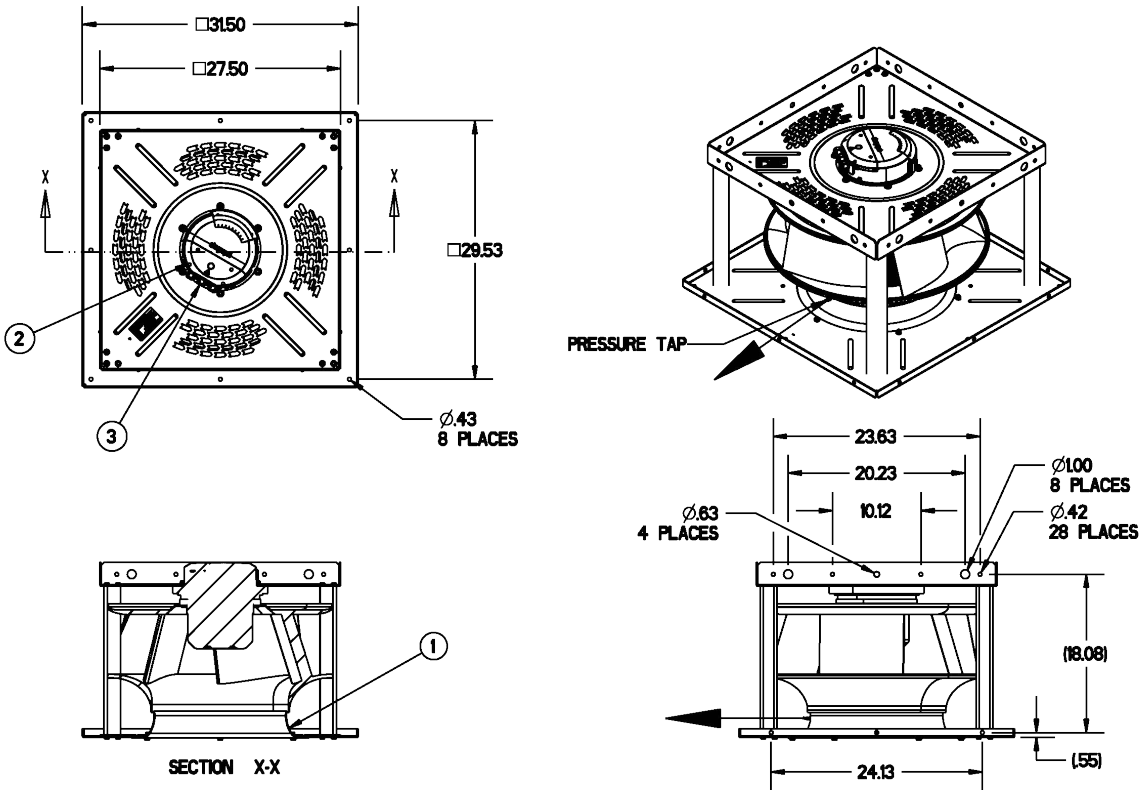
ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description	
Weight	140 lb (63.5 kg)
Nominal Impeller Size	22 in (560 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

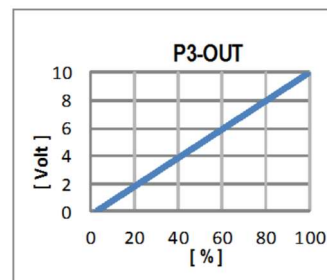
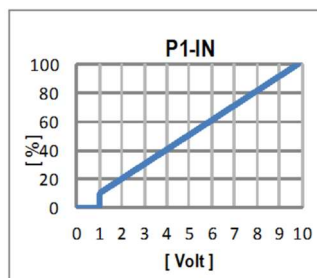
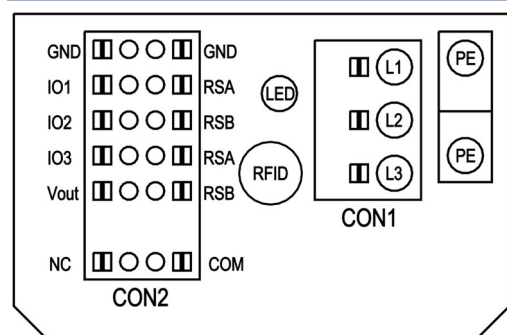
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 348 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79560-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00631-2-2957 (not included in scope of delivery)

Electrical Interface



No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

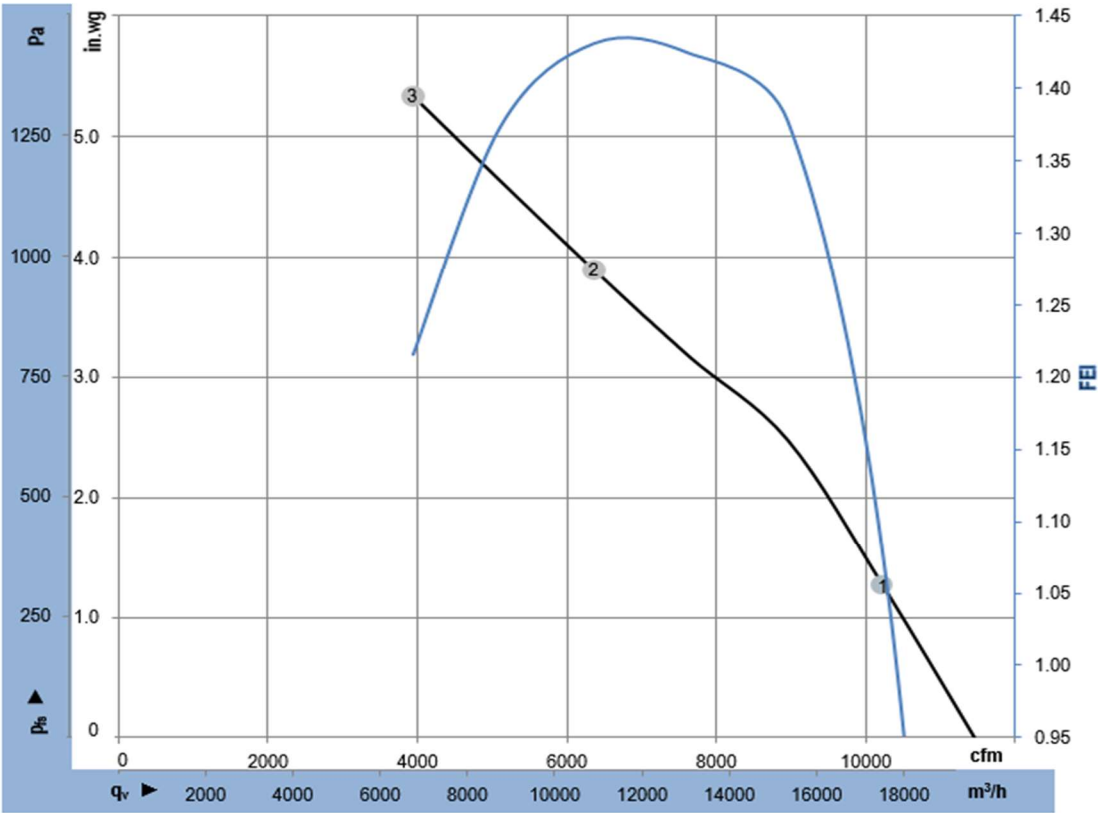
Terminal assignment

configurable IO functions: normal / inverse	MODBUS Register for IO mode configuration	electrical specification	CON2 configurable IO mode	OUTPUT															
				D101 [...]	D147 [...]	D104 [...]	D12E [...]	D148 [...]	D16C [...]	D16A [...]	signal: tach out (selected directly via IO mode)	signal: diagnostics out (selected directly via IO mode)	D130 [0]	D130 [1]	D130 [2]	D130 [3]	D130 [4]	D00C [1]	D130 [4]
				source: set value	source: sensor value	switch: parameter set: #1 / #2	switch: control function: heating (pos.) / cooling (neg.)	switch: direction of rotation: cw / ccw	switch: set value source	switch: fan enable / disable			signal: fan modulation level %	signal: actual speed	signal: system modulation level %	signal: remote control output 0-10V	pulse input for auto-addressing	pulse output for auto-addressing	

o configurable option

For further information and additional functions see EC Control Software, Fan-Set-App,
or MODBUS Parameter Specification V6.3

CON2	configurable IO mode	electrical specification	configurable IO functions: normal / inverse
IO1	o Din1 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D158 [0]
	o Ain1 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV	D158 [2]
	o Tach out (open collector output)	Umax = 50VDC, Imax = 20mA SELV	D158 [5]
	o Diagnostics out (open collector output)	Umax = 50VDC, Imax = 20mA SELV	D158 [6]
IO2	o Din2 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D159 [0]
	o Ain2 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV	D159 [2]
	o Ain2 4-20mA: analog input	Ri = 125R, characteristic curve parameterizable, SELV	D159 [3]
	o Din3 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC	D15A [0]
IO3	o Din3 (active low): digital input	active: applied voltage < 1,5VDC, SELV not active: pin open or applied voltage 3,5-50VDC	D15A [1]
	o PWMIn3: digital input idle level high	PWM = 40Hz - 10kHz, characteristics parameterizable active: pin open or applied voltage 3,5-50VDC not active: applied voltage < 1,5VDC, SELV	D15A [7]
	o PWMIn3: digital input idle level low	40Hz - 10kHz, characteristics parameterizable active: applied voltage 3,5-50VDC not active: pin open or applied voltage < 1,5VDC, SELV	D15A [8]
	o Aout3 0-10V: analog output	function parameterizable, max. 5mA max output frequency 300Hz SELV	D15A [4]
	o Tacho out (pulses), analog output	0-10V max. 5mA, max output frequency 300Hz SELV	D15A [5]
	o Diagnostics out (pulses)	0-10V max. 5mA max output frequency 300Hz SELV	D15A [6]
RSA RSB	RS485 bus connection,	MODBUS RTU, specification V6.3, SELV	
Vout	voltage output	voltage parameterizable 3,3...24VDC +/- 5%, Pmax=800mW, short-circuit-proof, supply for external devices, SELV	D16E [...]
	alternatively: Input auxiliary power supply for parameterization via RS485/MODBUS RTU without line voltage	15...50VDC	



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-2037

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	1700	3730	5.0	10235	1.3	1.07
2	3~	460	60	1656	4485	6.0	6358	3.9	1.43
3	3~	460	60	1700	4494	6.0	3934	5.3	1.22

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R240560C	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200-240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	1765
Power consumption	W	5483
Current draw	A	14.6
Min ambient temp	°F (°C)	-13 (-25)
Max ambient temp	°F (°C)	104 (40)

ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

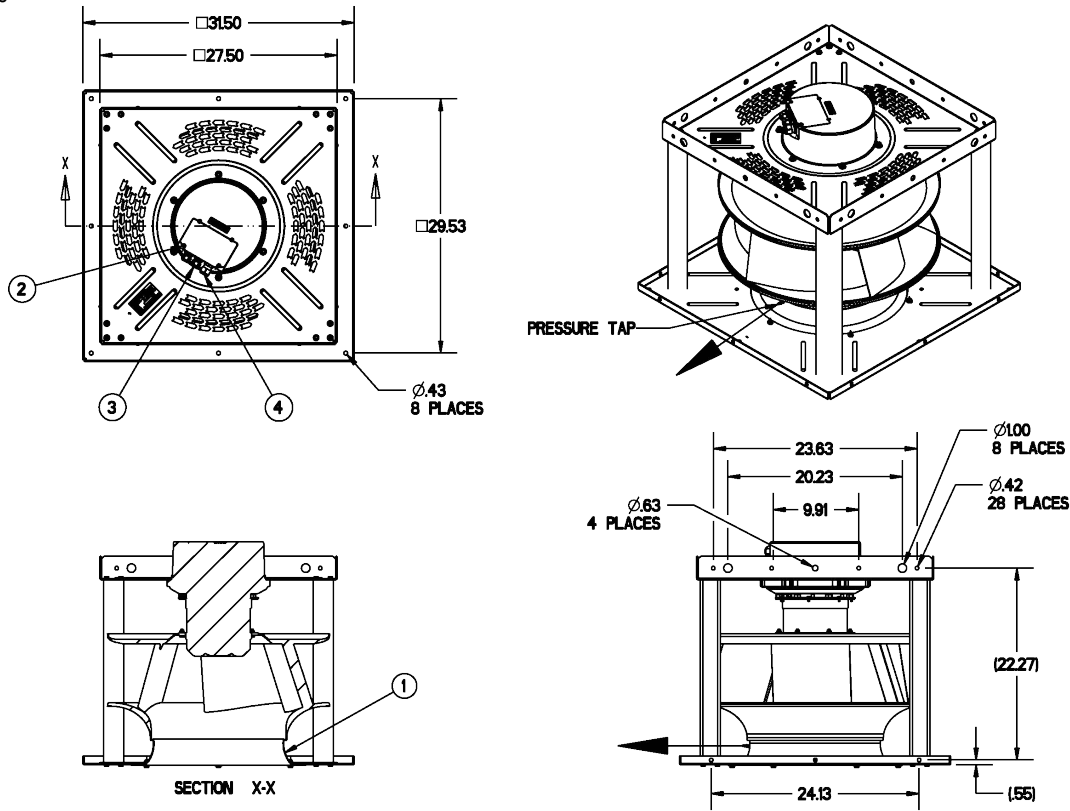
Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description

Weight	169 lb (77 kg)
Nominal Impeller Size	22 in (560 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 VDC - Input for sensor 0-10 VDC or 4-20 mA - External 24 VDC input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Motor protection	Reverse polarity and locked-rotor protection
Electrical hookup	Terminal box
Protection class	I (with customer connection of protective earth)
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

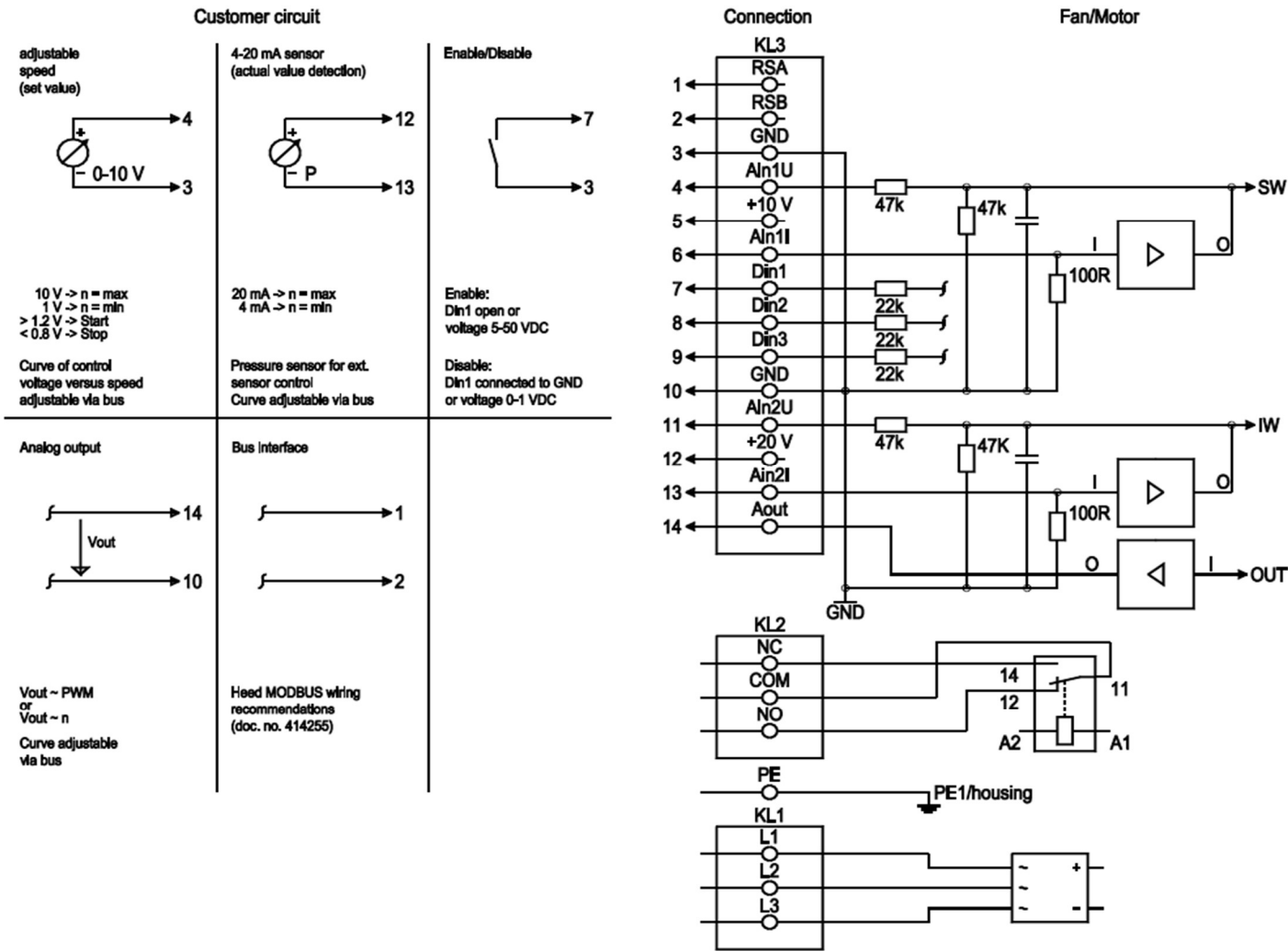
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 348 (available on some variations)
2	Terminal cover tightening torque: 30.9± 4.4 in-lbs (3.5±0.5 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm)
4	Cable diameter: 0.35-0.62 in (9-16 mm) Cable gland tightening torque: 53.1±7.9 in-lbs (6±0.9 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79560-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00631-2-2957 (not included in scope of delivery)

Electrical Interface

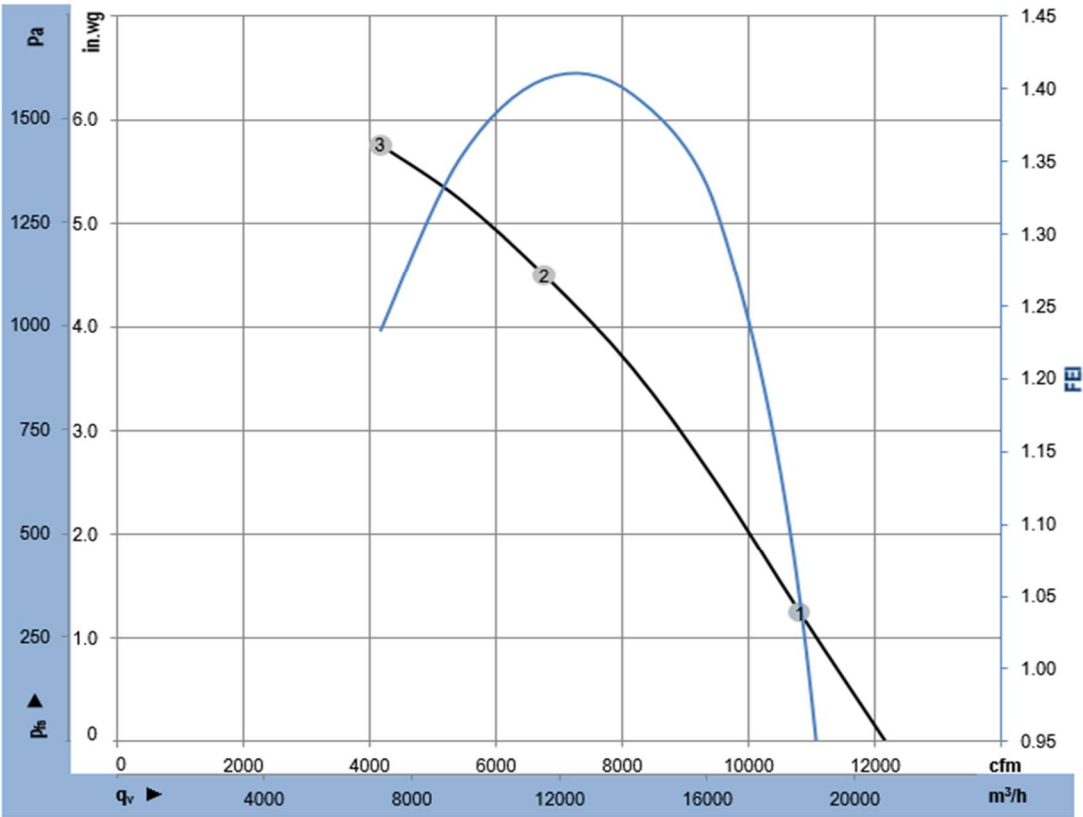


Terminal assignment

Terminal box connection diagram



No.	Conn.	Designation	Function/Assignment
KL1	1,2,3	L1, L2, L3	Power supply, phase, see nameplate for voltage range
PE	PE	PE	Protective earth
KL2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL3	1	RSA	Bus connection RS485, RSA, MODBUS RTU; SELV
KL3	2	RSB	Bus connection RS485, RSB, MODBUS RTU; SELV
KL3	3/10	GND	Reference ground for control interface; SELV
KL3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ± 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL3 KL3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV
KL3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL3	9	Din3	Digital input 3: Direction of action of integrated controller, according to EEPROM setting, the direction of action of the integrated controller can be selected as normal/inverse via bus or digital input Normal: Pin open or applied voltage 5-50 VDC Inverse: Bridge to GND or applied voltage < 1 VDC; SELV
KL3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ± 25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level; adjustable curve; SELV



$\rho = 0.075 \text{ lbm/ft}^3$
Measurement: LU-2089
ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	230	60	1769	3989	10.7	10815	1.2	1.04
2	3~	230	60	1767	5483	14.6	6761	4.5	1.41
3	3~	230	60	1765	4992	13.3	4163	5.8	1.23

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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Nominal Data

Model	EG1R480560C	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	1765
Power consumption	W	5256
Current draw	A	7.0
Min ambient temp	°F (°C)	-40 (-40)
Max ambient temp	°F (°C)	104 (40)

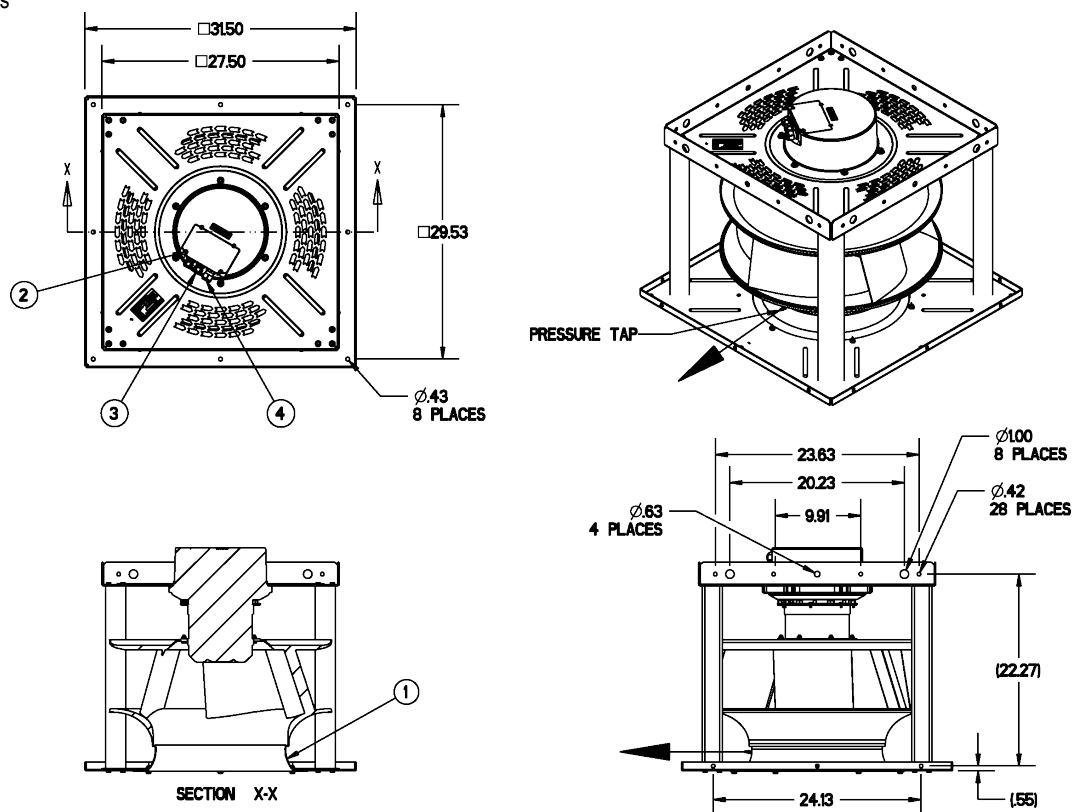
ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description	
Weight	169 lb (77 kg)
Nominal Impeller Size	22 in (560 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output for slave 0-10 VDC - External 24 VDC input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Motor protection	Reverse polarity and locked-rotor protection
Electrical hookup	Terminal box
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

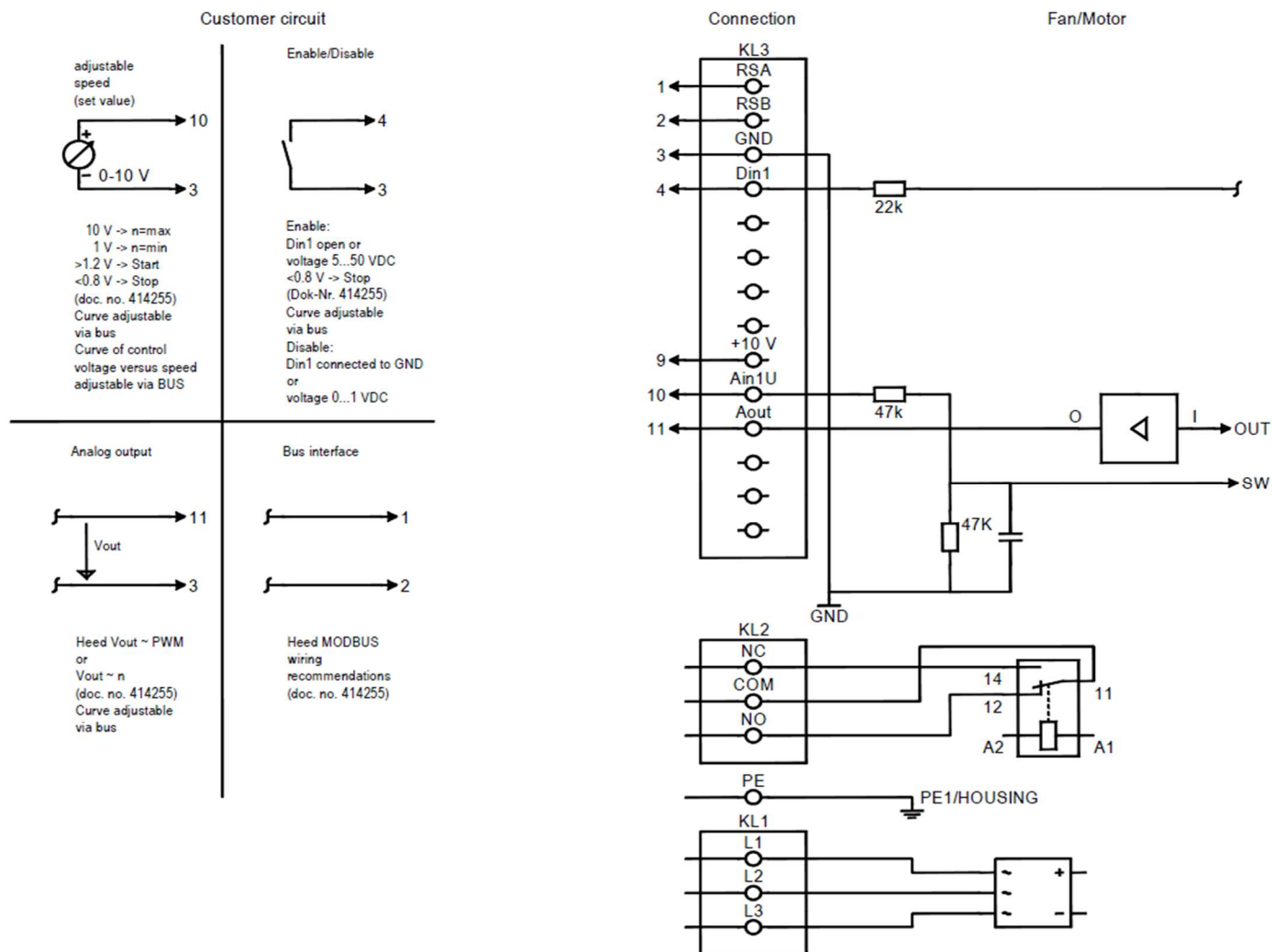
Product drawing

Dimensions in inches



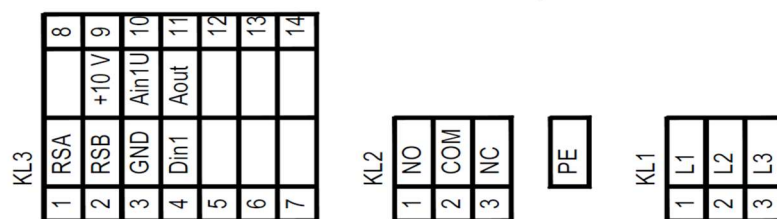
1	Inlet ring with pressure tap K-factor (m ³ /h & Pa): 348 (available on some variations)
2	Terminal cover tightening torque: 30.9± 4.4 in-lbs (3.5±0.5 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm)
4	Cable diameter: 0.35-0.62 in (9-16 mm) Cable gland tightening torque: 53.1±7.9 in-lbs (6±0.9 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79560-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00631-2-2957 (not included in scope of delivery)

Electrical Interface

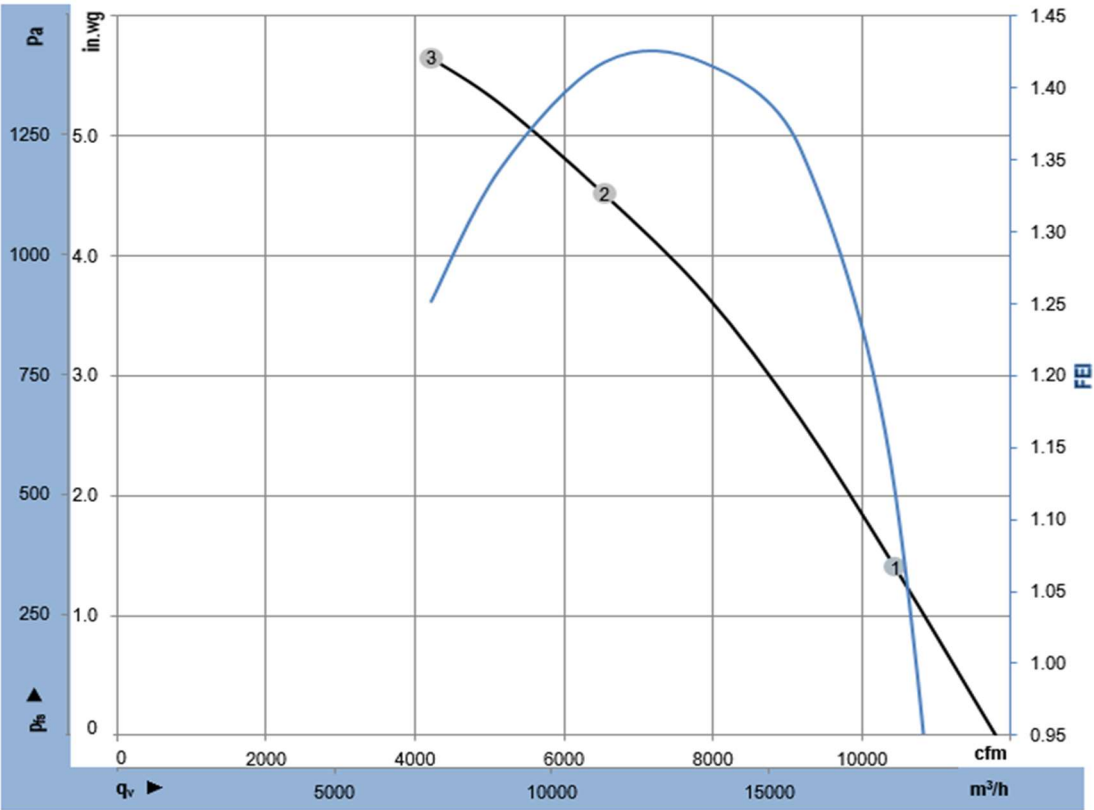


Terminal assignment

Terminal box connection diagram



No.	Conn.	Designation	Function/Assignment
KL1	1,2,3	L1, L2, L3	Power supply, phase, see nameplate for voltage range
PE	PE	PE	Protective earth
KL2	1	NO	Status relay, floating status contact, option 1: make for failure, option 2: make for error for run monitor
KL2	2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; basic insulation on supply side and reinforced insulation on control interface side
KL2	3	NC	Status relay, floating status contact, option 1: break for failure, option 2: break for error message for run monitor
KL3	1	RSA	RS485 interface for MODBUS, RSA; SELV
KL3	2	RSB	RS485 interface for MODBUS, RSB; SELV
KL3	3	GND	Reference ground for control interface; SELV
KL3	4	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-
KL3	-	-	-
KL3	9	+10 V	Voltage output 10 V/max. 10 mA, power supply for external devices (e.g. potentiometers), SELV
KL3	10	Ain1U	Analog input 1, set value: 0-10 VDC, Ri = 100 kΩ, adjustable curve; SELV
KL3	11	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV
KL3	-	-	
KL3	-	-	
KL3	-	-	



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-2087

ebm-papst Inc. certifies that the RadiPac - Modular EC Plenum Fan shown herein is licensed to bear the AMCA Seal. The ratings shown are based on tests and procedures performed in accordance with AMCA Publication 211 and comply with the requirements of the AMCA Certified Ratings Program.



Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	1766	3957	5.3	10458	1.4	1.12
2	3~	460	60	1764	5301	7.1	6548	4.5	1.42
3	3~	460	60	1765	4901	6.6	4224	5.6	1.25

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.

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www.ebmpapst.us

Nominal Data

Model	EG1R480630A	
Motor	M3G150-NA	
Phase		3~
Nominal voltage	VAC	460
Nominal voltage range	VAC	400-480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed	rpm	1505
Power consumption	W	4540
Current draw	A	6.1
Min. ambient temp	°F (°C)	-40 (-40)
Max. ambient temp	°F (°C)	104 (40)

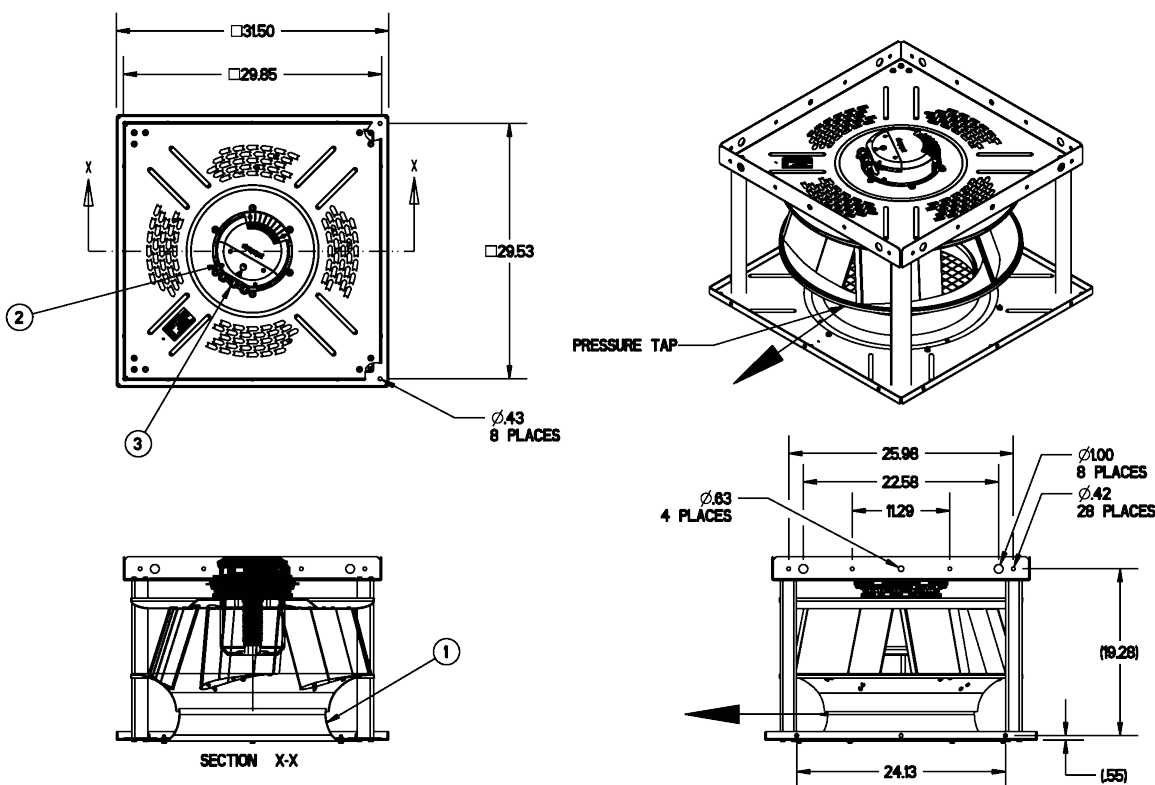
ml = Max. load (maximum fan input power over the range cataloged)
Subject to change

Speed (rpm) shown is nominal.
Performance is based on actual speed of test.

Technical Description	
Weight	160 lb (72.5 kg)
Nominal Impeller Size	24.8 in (630 mm)
Motor size	150
Rotor surface	Painted black
Impeller Material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Inlet plate material	Sheet steel, galvanized
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	F
Environmental class	H1
Ambient temp. note	Occasional startup between -40 °F & -13 °F (-40 °C & -25 °C) is permitted. For continuous operation below -13 °F (-25 °C), use a fan design with special low-temp bearings.
Max. ambient temp.	176 °F (+80 °C) (for motor transport/storage)
Min. ambient temp.	-40 °F (-40 °C) (for motor transport/storage)
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drain holes	On rotor side
Mode	S1
Motor bearing	Ball bearings
Technical features	<ul style="list-style-type: none"> - Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current	≤ 3.5 mA (according to IEC60990; measuring circuit Fig.4, TN system)
Electrical hookup	Terminal box
Motor protection	Electronic motor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approvals	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

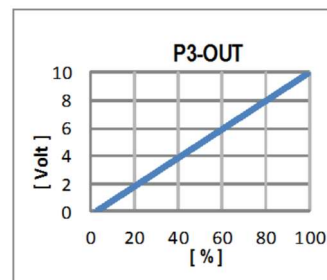
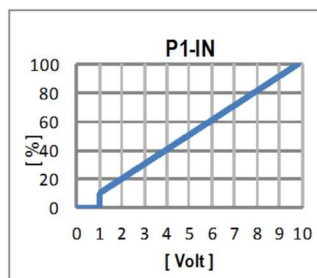
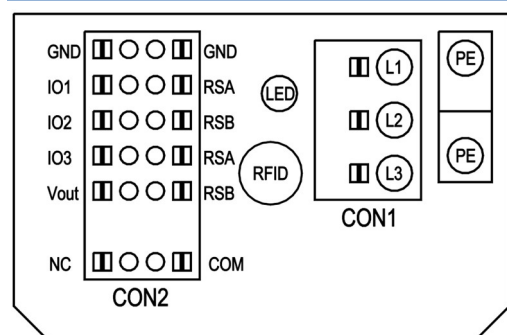
Product drawing

Dimensions in inches



1	Inlet ring with pressure tap K-factor (m³/h & Pa): 438 (available on some variations)
2	Terminal cover tightening torque: 13.2± 1.7 in-lbs (1.5±0.2 Nm)
3	Cable diameter: 0.15-0.39 in (4-10 mm) Cable gland tightening torque: 35.4±5.3 in-lbs (4±0.6 Nm) Please contact ebm-papst if conduit is required
	In a shaft horizontal orientation, the cable glands need to be located at the bottom and the cables must always be routed downwards
	Accessory part: Inlet finger guard p/n 79630-2-4039 (available on some variations)
	Accessory part: FlowGrid p/n 00631-2-2957 (not included in scope of delivery)

Electrical Interface



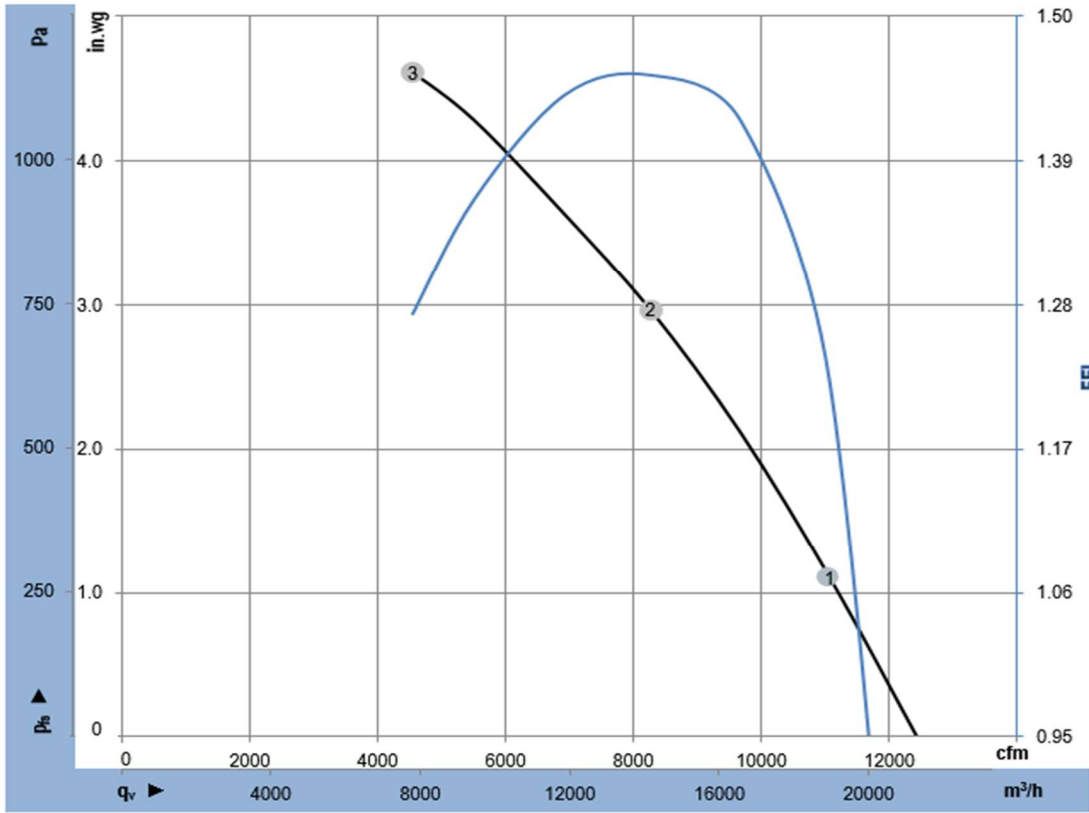
No.	Conn.	Desig.	Function/ Assignment
	CON1	L1,L2,L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 VDC / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 VDC, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

Terminal assignment

CON2	configurable IO mode	electrical specification	configurable IO functions: normal / inverse	MODBUS Register for IO mode configuration	D158 [0]	D158 [2]	D158 [5]	D158 [6]	D159 [0]	D159 [2]	D159 [3]	D15A [0]	D15A [1]	D15A [7]	D15A [8]	D15A [4]	D15A [5]	D15A [6]	D16E [..]
IO1	○ Din1 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC																	
	○ Ain1 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV																	
	○ Tacho out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV																	
	○ Diagnostics out (open collector output)	Umax = 50VDC, Imax = 20mA, SELV																	
IO2	○ Din2 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC																	
	○ Ain2 0-10V/PWM: analog input	Ri = 100K, characteristic curve parameterizable, $f_{PWM} = 1k, 10kHz$ SELV																	
	○ Ain2 4-20mA: analog input	Ri = 125R, characteristic curve parameterizable, SELV																	
	○ Din3 (active high): digital input	active: applied voltage 3,5-50VDC, SELV not active: pin open or applied voltage < 1,5VDC																	
IO3	○ Din3 (active low): digital input	active: applied voltage < 1,5VDC, SELV not active: pin open or applied voltage 3,5-50VDC																	
	○ PWMIn3: digital input idle level high	PWM = 40Hz - 10kHz, characteristics parameterizable active: pin open or applied voltage 3,5-50VDC not active: applied voltage < 1,5VDC, SELV																	
	○ PWMIn3: digital input idle level low	40Hz - 10kHz, characteristics parameterizable active: applied voltage 3,5-50VDC not active: pin open or applied voltage < 1,5VDC, SELV																	
	○ Aout3 0-10V: analog output	function parameterizable, max. 5mA max output frequency 300Hz SELV																	
RSA RSB	○ Tacho out (pulses), analog output	0-10V max. 5mA, max output frequency 300Hz SELV																	
	○ Diagnostics out (pulses)	0-10V max. 5mA, max output frequency 300Hz SELV																	
	○ RSA RSB bus connection,	MODBUS RTU, specification V6.3, SELV																	
	voltage output	voltage parameterizable 3.3...24VDC +/- 5%, Pmax=800mW, short-circuit-proof, supply for external devices, SELV																	
Vout	alternatively: Input auxiliary power supply for parameterization via RS485MODBUS RTU without line voltage	15...50VDC																	

○ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.3



$\rho = 0.075 \text{ lbm/ft}^3$

Measurement: LU-2099

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Performance Ratings

		U	f	n	P _{ed}	I	q _v	p _{is}	FEI
		V	Hz	rpm	W	A	cfm	in. wg	
1	3~	460	60	1505	3227	4.4	11074	1.1	1.22
2	3~	460	60	1503	4455	6.0	8266	3.0	1.46
3	3~	460	60	1503	4302	5.8	4554	4.6	1.27

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Electrical power · I = Current draw · q_v = Air flow · p_{is} = Pressure increase

Performance certified is for installation type A - Free inlet, Free outlet.
Rating Method "E" (Direct Drive, As Run Speed)
Performance ratings include the effects of support brackets.